

# 基于运输的方法

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# 本堂课大纲

## ➤ 课程内容简介

- 重要性采样 (Importance sampling)
- 卡尔曼方法 (Kalman methodology)
- 标准化流 (Normalizing flow)



# 贝叶斯反问题

## ➤ 贝叶斯反问题

$$y = \mathcal{G}(\theta) + \eta \quad \eta \sim \rho_\eta \quad \theta \sim \rho_{\text{prior}}$$

## ➤ 假设

$$\text{高斯先验分布: } \rho_{\text{prior}}(\theta) = \mathcal{N}(\theta; r_0, \Sigma_0)$$

$$\text{高斯噪音: } \rho_\eta = \mathcal{N}(x; 0, \Sigma_\eta)$$

## ➤ 后验分布

$$\rho_{\text{post}}(\theta; y) \propto \rho(y|\theta)\rho_{\text{prior}}(\theta) \propto e^{-\Phi_R(\theta, y)}$$

$$\rho_{\text{post}}(\theta; y) = \frac{1}{Z} e^{-\Phi_R(\theta, y)}$$

$$\Phi_R(\theta, y) = \frac{1}{2} \|\Sigma_\eta^{-\frac{1}{2}} (y - \mathcal{G}(\theta))\|^2 + \frac{1}{2} \|\Sigma_0^{-\frac{1}{2}} (\theta - r_0)\|^2$$



# 贝叶斯采样、推理

➤ 有未知归一化常数的目标分布

$$\rho^*(\theta) = \frac{1}{Z} e^{-\Phi_R(\theta)}$$

未知  $\nearrow$   $\leftarrow$  已知

$$\Phi_R(\theta, y) = \frac{1}{2} \|\Sigma_\eta^{-\frac{1}{2}} (y - \mathcal{G}(\theta))\|^2 + \frac{1}{2} \|\Sigma_0^{-\frac{1}{2}} (\theta - r_0)\|^2$$

- 计算目标分布的期望、协方差等
- 计算目标函数的期望  $\mathbb{E}[f] = \int f(\theta) \rho^*(\theta) d\theta$
- 生成服从目标分布的样本  $\{\theta_j\} \sim \rho^*(\theta)$



# 贝叶斯采样、推理

## ➤ 基于输运的方法（直接近似的方法）

暴力网格搜索：假设  $N_\theta = 2$ ,

$$\theta^{i,j} = \left[ -L + \frac{2(i-1)}{N-1} L, -L + \frac{2(j-1)}{N-1} L \right] Z = \sum \rho^*(\theta^{i,j}) \text{ 输运：}$$

$$\{\theta^j\} \sim \rho_{\text{prior}} \quad \{\mathcal{T}\theta^j\} \sim \rho^*$$

- 重要性采样
- 卡尔曼方法
- 标准化流方法
- .....



# 重要性采样

## ▶ 蒙特卡洛方法

$$\text{计算: } \mathbb{E}_{\rho^*}[f] = \int f(\theta)\rho^*(\theta)d\theta$$

$$\text{采样: } \{\theta^j\} \sim \rho^*(\theta)$$

$$\mathbb{E}_{\rho^*}[f] \approx \rho_{\text{MC}}^J(f) = \frac{1}{J} \sum_{j=1}^J f(\theta^j)$$



# 重要性采样

## 蒙特卡洛方法收敛性

对于  $f: R^{N_\theta} \rightarrow R$ ,  $\text{Var}_\rho[f] = \mathbb{E}_\rho \left[ (f - \mathbb{E}_\rho f)^2 \right] < +\infty$

我们有

$$\mathbb{E}_\rho \left[ \frac{1}{J} \sum_{j=1}^J f(\theta^j) - \mathbb{E}_\rho[f] \right] = 0$$

$$\mathbb{E}_\rho \left[ \left( \frac{1}{J} \sum_{j=1}^J f(\theta^j) - \mathbb{E}_\rho[f] \right)^2 \right] = \frac{\text{Var}_\rho[f]}{J}$$



# 重要性采样

## ► 重要性采样

$$\rho^*(\theta) = \frac{1}{Z} e^{-\Phi(\theta)} \rho(\theta)$$

采样： $\{\theta^j\} \sim \rho(\theta)$

计算： $\Phi(\theta^j)$

$$\text{计算权重： } w_j = \frac{e^{-\Phi(\theta^j)}}{\sum_{j=1}^J e^{-\Phi(\theta^j)}}$$

输运： $\{\theta^j\} \rightarrow \{w^j \theta^j\}$

$$\rho^*(\theta) \approx \sum_{j=1}^J w_j \delta(\theta - \theta^j)$$

$$\mathbb{E}_{\rho^*}[f] \approx \rho^* \int_{\text{IS}}(f) = \sum_{j=1}^J w^j f(\theta^j)$$





# 重要性采样

## 重要性采样方法收敛性

对于  $f: R^{N\theta} \rightarrow R$ ,  $\chi^2[\rho^* \|\rho] = \int \frac{\rho^{*2}}{\rho} d\theta - 1$ ,

我们有

$$\sup_{|f|_{\infty} \leq 1} \mathbb{E}_{\rho} \left[ \rho^{*J}_{\text{IS}}(f) - \mathbb{E}_{\rho^*}[f] \right] \leq 2 \frac{1 + \chi^2[\rho^* \|\rho]}{J}$$

$$\sup_{|f|_{\infty} \leq 1} \mathbb{E}_{\rho} \left[ \left( \rho^{*J}_{\text{IS}}(f) - \mathbb{E}_{\rho^*}[f] \right)^2 \right] \leq 4 \frac{1 + \chi^2[\rho^* \|\rho]}{J}$$



# 重要性采样

## ➤ 练习 (Rosenbrock 函数)

$$y = G(\theta) + \eta$$

$$G(\theta) = \begin{bmatrix} \theta_2 - c_1 \theta_1^2 \\ \theta_1 \end{bmatrix} \quad y = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

高斯先验分布： $\rho_{\text{prior}}(\theta) = \mathcal{N}(\theta; 0, \begin{bmatrix} 10^2 & \\ & 10^2 \end{bmatrix})$

高斯噪音： $\rho_{\eta} = \mathcal{N}\left(x; 0, \begin{bmatrix} \frac{1}{10^2} & \\ & 1 \end{bmatrix}\right)$

后验分布： $\rho^*(\theta) = \frac{1}{Z} e^{-\Phi(\theta)} \rho_{\text{prior}}(\theta)$

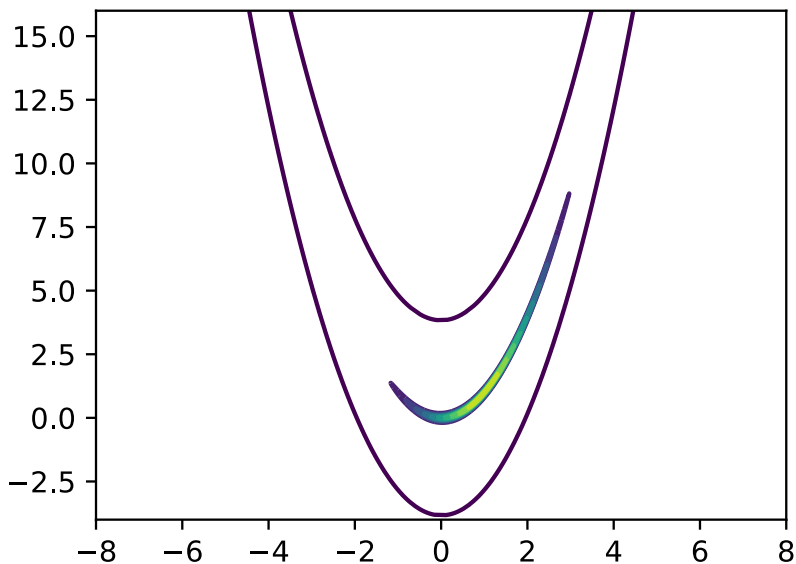
考虑： $c_1 = 10^{-2}$ , 1, 计算 $\theta$ 的期望。



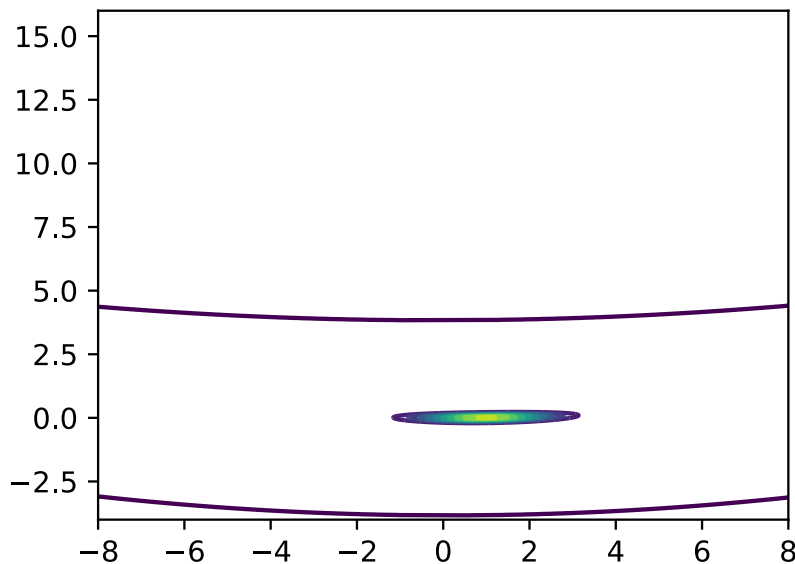
# 重要性采样

## 练习 (Rosenbrock 函数)

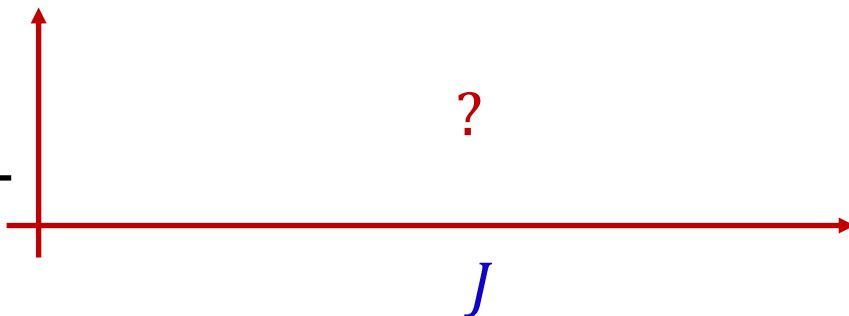
$c_1 = 10^{-2}$



$c_1 = 1$



$$\frac{\text{norm}(\rho_{\text{IS}}^{*J}(\theta) - \mathbb{E}_{\rho^*}[\theta])}{\text{norm}(\mathbb{E}_{\rho^*}[\theta])}$$

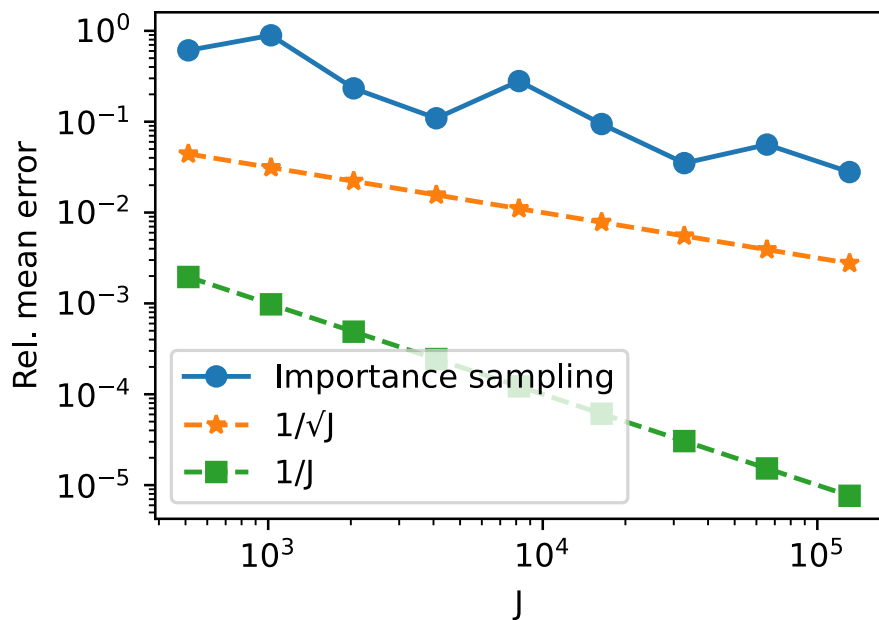




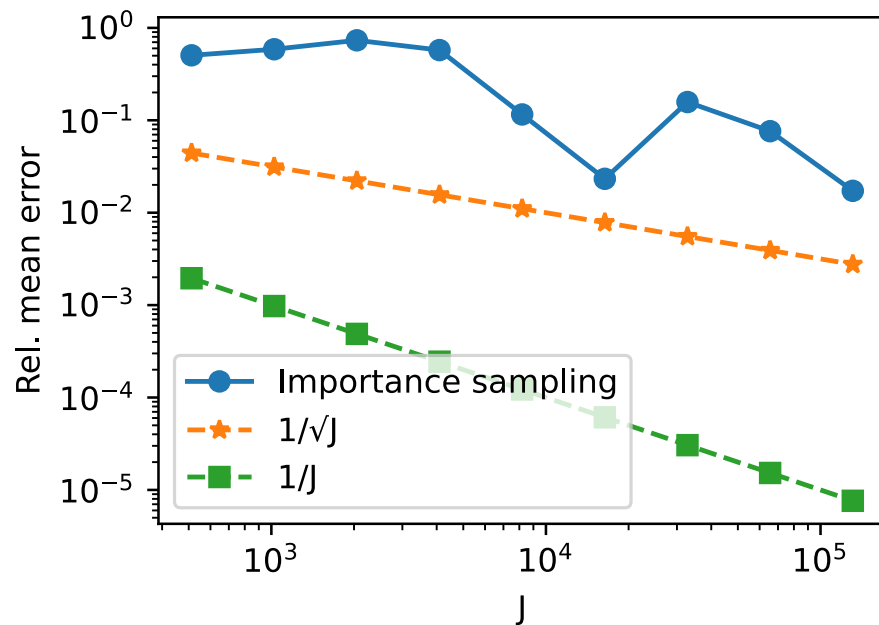
# 重要性采样

## 练习 (Rosenbrock 函数)

$$c_1 = 10^{-2}$$



$$c_1 = 1$$





# 卡尔曼(Kalman)方法

## ➤ 贝叶斯反问题

$$y = G(\theta) + \eta \quad \eta \sim \rho_\eta \quad \theta \sim \rho_{\text{prior}}$$

## ➤ 假设

高斯先验分布:  $\rho_{\text{prior}}(\theta) = \mathcal{N}(\theta; r_0, \Sigma_0)$

高斯噪音:  $\rho_\eta = \mathcal{N}(x; 0, \Sigma_\eta)$

## ➤ 贝叶斯法则

$$\rho(\theta|y) = \frac{\rho(\theta, y)}{\rho(y)} = \frac{\rho(y|\theta)\rho(\theta)}{\rho(y)}$$

$$\rho_{\text{prior}}(\theta) \rightarrow \rho(\theta, y) \rightarrow \rho_{\text{post}}(\theta)$$



# 卡尔曼方法

## ➤ 先验分布

$$\rho_{\text{prior}}(\theta) = \mathcal{N}(r_0, \Sigma_0)$$

## ➤ $\theta$ 和 $G(\theta) + \eta$ 的联合分布

$$\rho(\theta, G(\theta) + \eta) \approx \mathcal{N}\left(\begin{bmatrix} r_0 \\ \hat{y} \end{bmatrix}, \begin{bmatrix} \Sigma_0 & \hat{C}^{\theta y} \\ \hat{C}^{\theta y T} & \hat{C}^{yy} \end{bmatrix}\right)$$

$$\hat{y} = \mathbb{E}[G(\theta) + \eta] \quad \hat{C}^{\theta y} = \text{Cov}[\theta, G(\theta) + \eta] \quad \hat{C}^{yy} = \text{Cov}[G(\theta) + \eta]$$

## ➤ 后验分布 (条件分布)

$$\rho(\theta | G(\theta) + \eta = y) = \mathcal{N}(m, C)$$

$$m = r_0 + \hat{C}^{\theta y} (\hat{C}^{yy})^{-1} (y - \hat{y})$$

$$C = \Sigma_0 - \hat{C}^{\theta y} (\hat{C}^{yy})^{-1} \hat{C}^{\theta y T}$$



# 卡尔曼方法

## ➤ 贝叶斯反问题

$$y = G(\theta) + \eta \quad \eta \sim \rho_\eta \quad \theta \sim \rho_{\text{prior}}$$

## ➤ 假设

高斯先验分布:  $\rho_{\text{prior}}(\theta) = \mathcal{N}(\theta; r_0, \Sigma_0)$

高斯噪音:  $\rho_\eta = \mathcal{N}(x; 0, \Sigma_\eta)$

## ➤ 如何计算

$$\hat{y} = \mathbb{E}[G(\theta) + \eta] \quad \hat{C}^{\theta y} = \text{Cov}[\theta, G(\theta) + \eta] \quad \hat{C}^{yy} = \text{Cov}[G(\theta) + \eta]$$



# 扩展 (Extended) 卡尔曼方法

► 泰勒展开线性化

$$g(\theta) \approx g(r_0) + \nabla g(r_0)(\theta - r_0)$$

$$\rho_{\text{prior}}(\theta) = \mathcal{N}(r_0, \Sigma_0) \quad \eta \sim \mathcal{N}(0, \Sigma_\eta)$$

$$\hat{y} = \mathbb{E}[g(\theta) + \eta] \approx g(r_0)$$

$$\hat{C}^{\theta y} = \text{Cov}[\theta, g(\theta) + \eta] \approx \Sigma_0 \nabla g(r_0)^T$$

$$\hat{C}^{yy} = \text{Cov}[g(\theta) + \eta] \approx \nabla g(r_0)^T \Sigma_0 \nabla g(r_0) + \Sigma_\eta$$





# 扩展 (Extended) 卡尔曼方法

## ➤ 线性贝叶斯反问题

$$C_{\text{post}} = \Sigma_0 - \Sigma_0 G^T (G \Sigma_0 G^T + \Sigma_\eta)^{-1} G \Sigma_0$$
$$m_{\text{post}} = r_0 - \Sigma_0 G^T (G \Sigma_0 G^T + \Sigma_\eta)^{-1} (G r_0 - y)$$

## ➤ 扩展卡尔曼方法

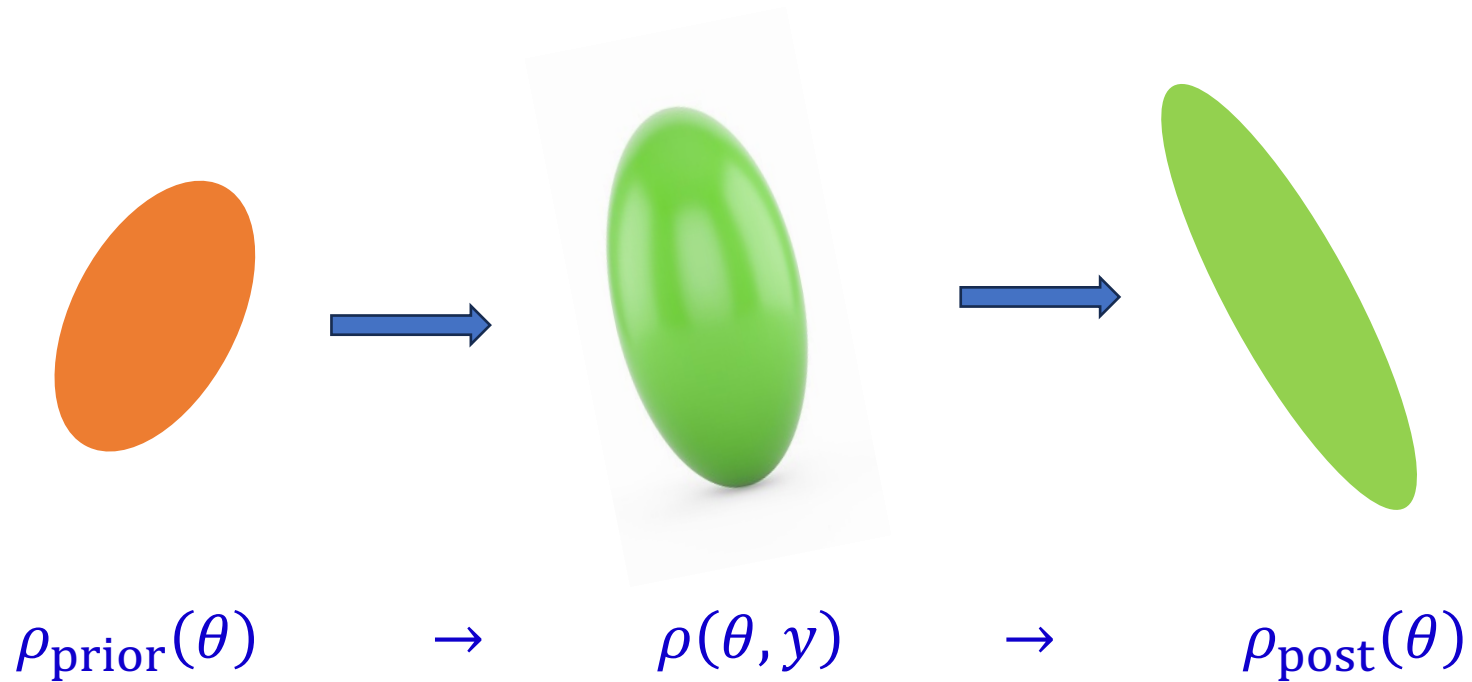
$$C_{\text{post}} = \Sigma_0 - \Sigma_0 \nabla G^T (\nabla G \Sigma_0 \nabla G^T + \Sigma_\eta)^{-1} \nabla G \Sigma_0$$
$$m_{\text{post}} = r_0 - \Sigma_0 \nabla G^T (\nabla G \Sigma_0 \nabla G^T + \Sigma_\eta)^{-1} (G(r_0) - y)$$



# 扩展 (Extended) 卡尔曼方法

## ➤ 输运

$$T: \mathcal{N}(r_0, \Sigma_0) \rightarrow \mathcal{N}(m, C)$$





# 无迹(Unscented)卡尔曼方法

## 无迹变换

对于高斯分布  $\theta \sim \mathcal{N}(m, C) \in \mathbb{R}^{N_\theta}$ , 我们选取  $2N_\theta + 1$  个  $\sigma$  点,  $\theta^0 = m$ , 对  $j = 1, 2, \dots, N_\theta$

$$\theta^j = m + c_j [\sqrt{C}]_j \quad \theta^{j+N_\theta} = m - c_j [\sqrt{C}]_j$$

其中  $[\sqrt{C}]_j$  是  $C$  的 Cholesky 分解的第  $j$  个列向量, 那么

$$\mathbb{E}[G(\theta)] \approx \hat{\mathbb{E}}[G(\theta)] := \sum_{i=0}^{2N_\theta} W_i^m G(\theta^i)$$

$$\text{Cov}[G_1(\theta), G_2(\theta)] \approx$$

$$\sum_{i=0}^{2N_\theta} W_i^c (G_1(\theta^i) - \hat{\mathbb{E}}[G_1(\theta)])(G_2(\theta^i) - \hat{\mathbb{E}}[G_2(\theta)])^T$$

参数:  $c_i, W_i^m, W_i^c$



# 无迹(Unscented)卡尔曼方法

## ➤ 无迹变换

对于高斯分布  $\theta \sim \mathcal{N}(m, C) \in R^{N_\theta}$ ，我们有

$$\mathcal{G}(\theta) = \mathcal{G}(m) + \nabla \mathcal{G} \delta \theta + \frac{1}{2} \nabla^2 \mathcal{G} \delta \theta \otimes \delta \theta + \frac{1}{6} \nabla^3 \mathcal{G} \delta \theta \otimes \delta \theta \otimes \delta \theta + \mathcal{O}(\delta \theta^4)$$

$$\mathbb{E}[\mathcal{G}(\theta)] = \mathcal{G}(m) + \frac{1}{2} \nabla^2 \mathcal{G} C + \mathcal{O}(\|C\|^2)$$

$$\text{Cov}[\mathcal{G}_1(\theta), \mathcal{G}_2(\theta)] = \nabla \mathcal{G}_1 C \nabla \mathcal{G}_2^T + \mathcal{O}(\|C\|^2)$$



# 无迹(Unscented)卡尔曼方法

## 无迹变换

当  $1 \leq j \leq N_\theta$

$$W_j^m = W_{j+N_\theta}^m \quad W_j^c = W_{j+N_\theta}^c = \frac{1}{2c_j^2} \quad \sum_{i=0}^{2N_\theta} W_i^m = 1$$

$$\begin{aligned} \sum_{i=0}^{2N_\theta} W_i^m \mathcal{G}(\theta^i) &= \mathbb{E}[\mathcal{G}(\theta)] + \\ &+ \sum_{j=1}^{N_\theta} c_j^2 W_j^m \nabla^2 \mathcal{G}[\sqrt{C}]_j \otimes [\sqrt{C}]_j + \mathcal{O}(\|C\|^2) \end{aligned}$$

$$\begin{aligned} \sum_{i=0}^{2N_\theta} W_i^c (\mathcal{G}_1(\theta^i) - \hat{\mathbb{E}}[\mathcal{G}_1(\theta)])(\mathcal{G}_2(\theta^i) - \hat{\mathbb{E}}[\mathcal{G}_2(\theta)])^T \\ = \text{Cov}[\mathcal{G}_1(\theta), \mathcal{G}_2(\theta)] + \mathcal{O}(\|C\|^2) \end{aligned}$$

我们选取  $W_0^m = 1$ ,  $W_0^c = 0$ , 对于  $1 \leq j \leq N_\theta$

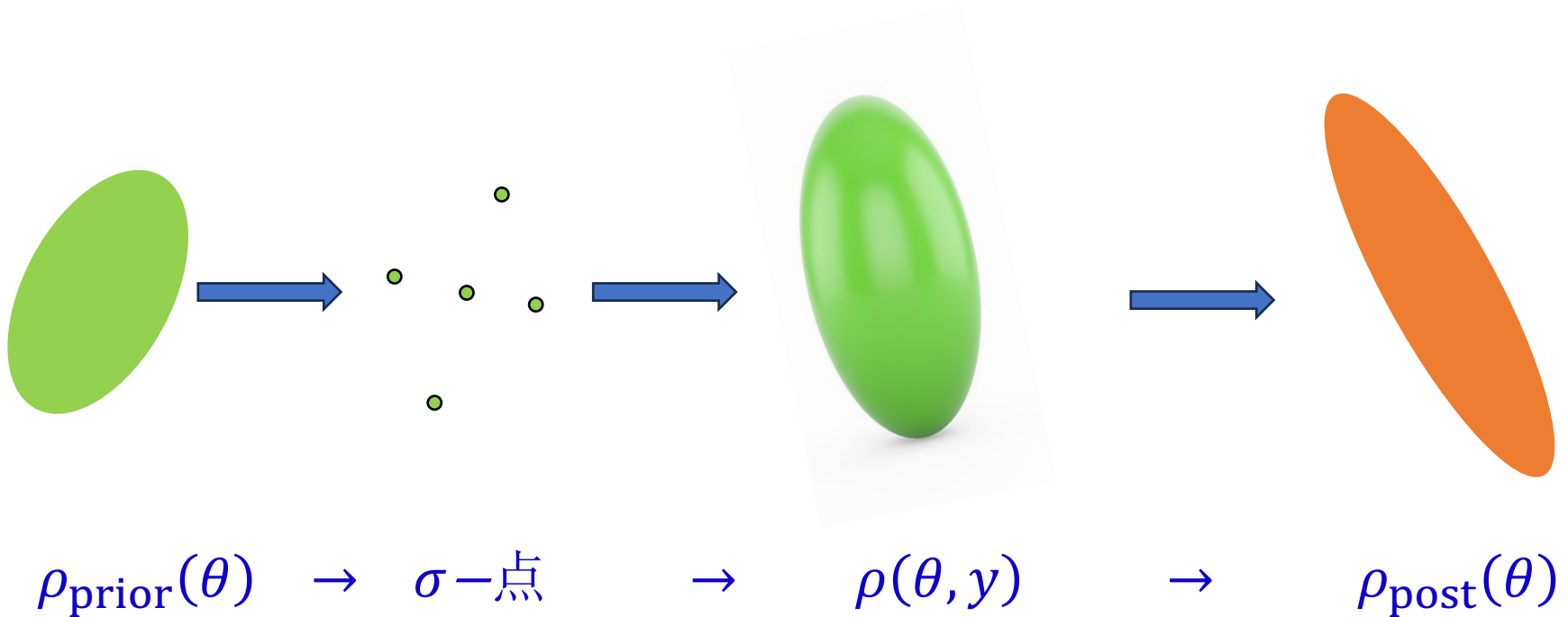
$$c_j = a\sqrt{N_\theta}, \quad W_j^m = 0, \quad W_j^c = \frac{1}{2a^2 N_\theta}$$



# 无迹(Unscented)卡尔曼方法

## ➤ 输运

$$\mathcal{T}: \mathcal{N}(r_0, \Sigma_0) \rightarrow \mathcal{N}(m, C)$$





# 集合卡尔曼方法

## ► 蒙特卡洛方法

$$\{\theta_j\} \sim \rho_{\text{prior}}(\theta) = \mathcal{N}(r_0, \Sigma_0) \quad \eta \sim \mathcal{N}(0, \Sigma_\eta)$$

$$\hat{y} = \frac{1}{J} \sum_{j=1}^J y^j \quad y^j = g(\theta^j)$$

$$\hat{y} = \mathbb{E}[g(\theta) + \eta] \approx \hat{y}$$

$$\hat{C}^{\theta y} = \text{Cov}[\theta, g(\theta) + \eta] = \frac{1}{J-1} \sum_{j=1}^J (\theta^j - r_0)(y^j - \hat{y})^T$$

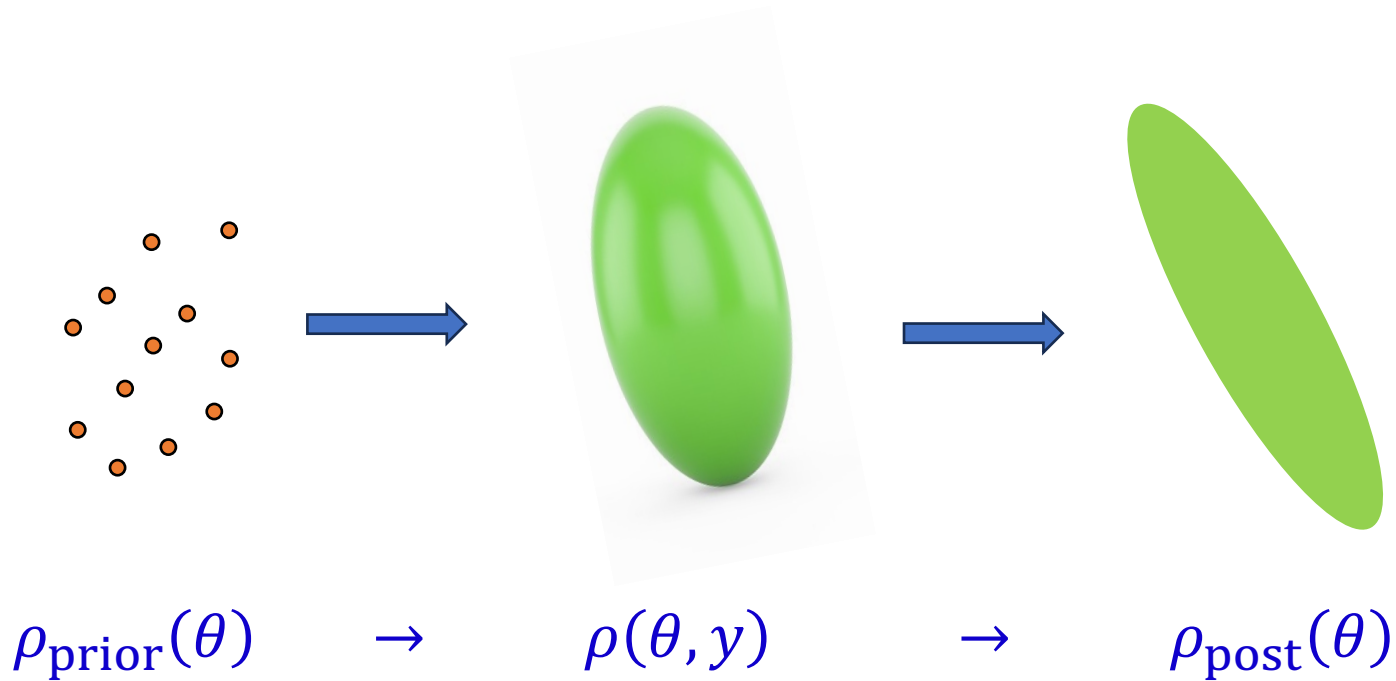
$$\hat{C}^{yy} = \text{Cov}[g(\theta) + \eta] = \frac{1}{J-1} \sum_{j=1}^J (y^j - \hat{y})(y^j - \hat{y})^T + \Sigma_\eta$$



# 集合(Ensemble)卡尔曼方法

## ► 输运

$$\mathcal{T}: \{\theta^j\} \rightarrow \mathcal{N}(m, C)$$



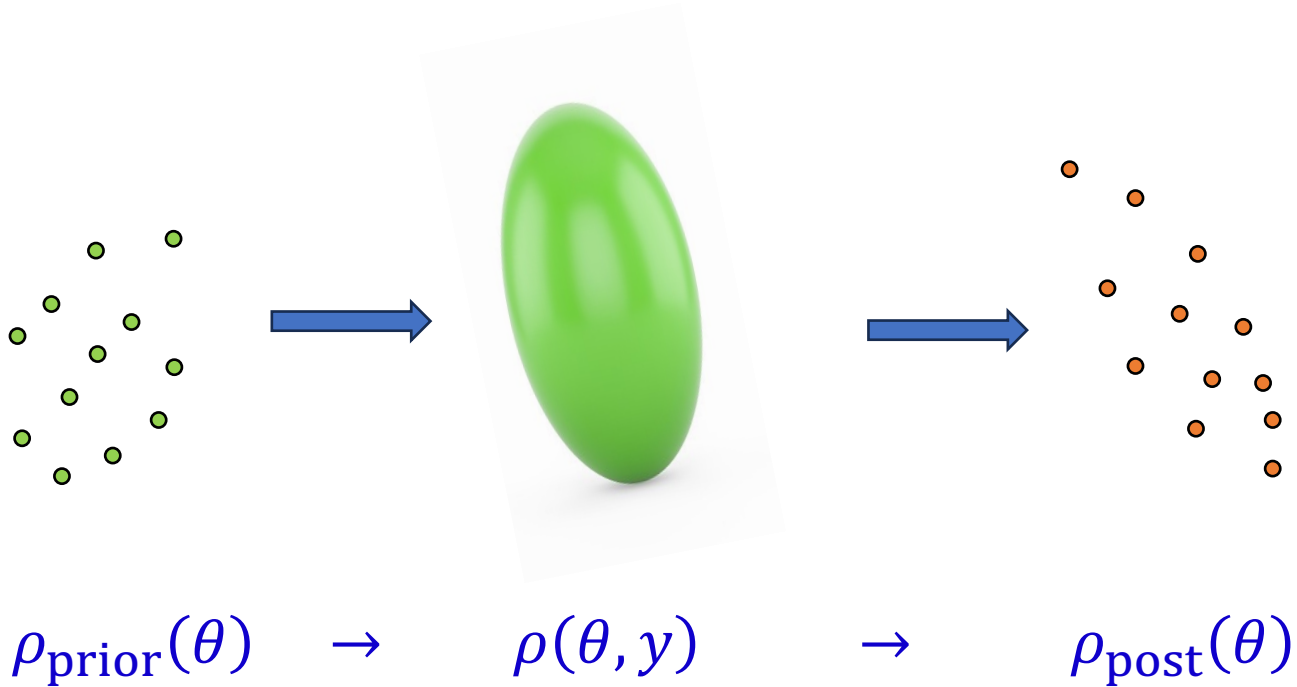




# 集合(Ensemble)卡尔曼方法

## ► 输运

$$\mathcal{T}: \{\theta^j\} \rightarrow \{\mathcal{T}\theta^j\}$$



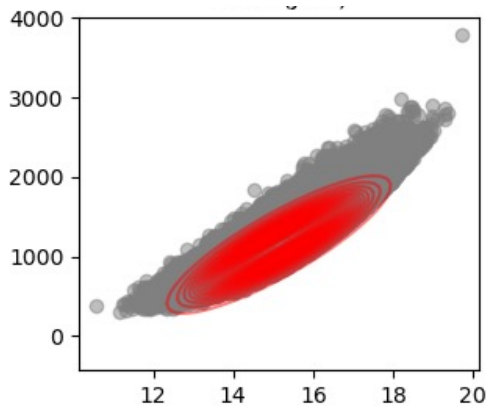


# 卡尔曼方法

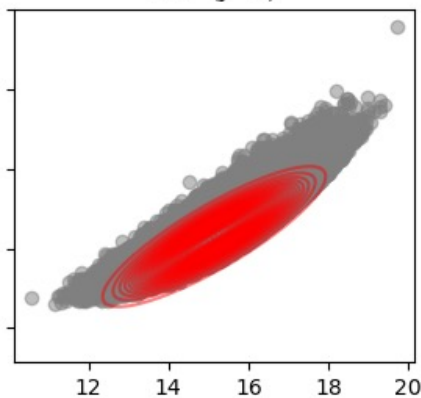
➤ 练习：计算 $G(\theta)$ 分布

$$\theta \sim \mathcal{N}\left(\begin{bmatrix} 10 \\ 10 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) \quad G(\theta) = \begin{bmatrix} 1 + \sqrt{\theta_{(1)}^2 + \theta_{(2)}^2} \\ \exp\frac{\theta_{(1)}}{2} + \theta_{(2)}^3 \end{bmatrix}$$

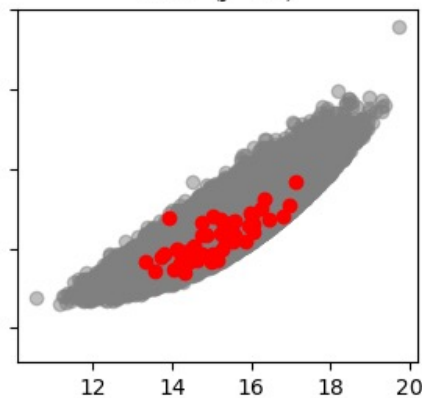
扩展卡尔曼方法  
 $J = 1$



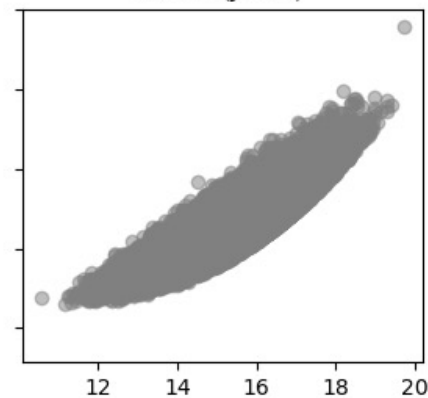
无迹卡尔曼方法  
 $J = 5$



集合卡尔曼方法  
 $J = 50$



标准  
 $J = 10^5$



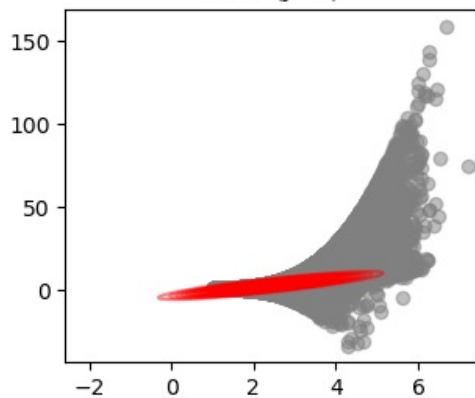


# 卡尔曼方法

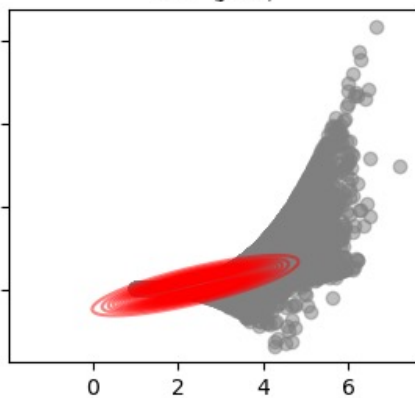
➤ 练习：计算 $g(\theta)$  分布

$$\theta \sim \mathcal{N}\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) \quad g(\theta) = \begin{bmatrix} 1 + \sqrt{\theta_{(1)}^2 + \theta_{(2)}^2} \\ \exp\frac{\theta_{(1)}}{2} + \theta_{(2)}^3 \end{bmatrix}$$

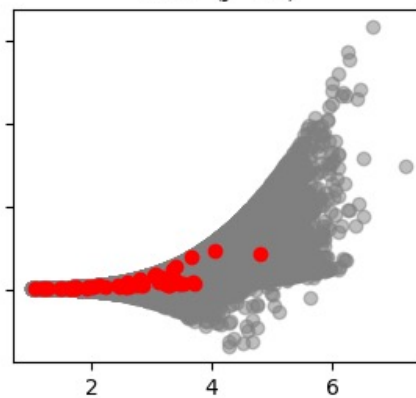
扩展卡尔曼方法  
 $J = 1$



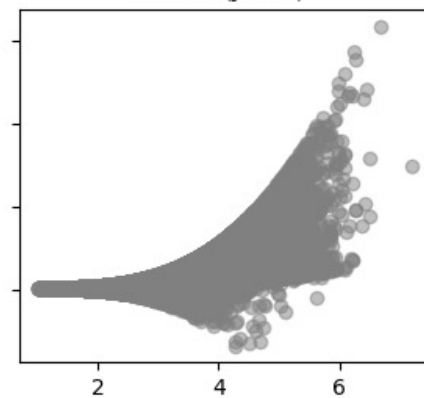
无迹卡尔曼方法  
 $J = 5$



集合卡尔曼方法  
 $J = 50$



标准  
 $J = 10^5$





# 标准化流(Normalizing flow)

- 有未知归一化常数的目标分布

$$\rho^*(\theta) = \frac{1}{Z} e^{-\Phi_R(\theta)}$$

- 标准化流

基于神经网络的映射  $\mathcal{T}_{NN}: R^{N_\theta} \rightarrow R^{N_\theta}$

$$\{\theta^j\} \sim \rho_{\text{prior}} \quad \rightarrow \quad \{\mathcal{T}_{NN}(\theta^j)\} \sim \rho^*$$

神经网络  $\mathcal{T}_{NN}$  : 参数化的非线性映射, 能自动计算关于参数或输入的导数



# 标准化流

➤ 诱导测度(Pushforward)

$$\mathcal{T}: \theta \rightarrow \tilde{\theta} = \mathcal{T}(\theta)$$

$$\mathcal{T}: \rho \rightarrow \tilde{\rho} = \mathcal{T}\#\rho \quad \rho(\theta) = \tilde{\rho}(\mathcal{T}(\theta))|\nabla_{\theta}\mathcal{T}(\theta)|$$

$$\begin{aligned} \int_{\theta \in A} \rho(\theta) d\theta &= \int_{\tilde{\theta} \in \mathcal{T}(A)} \tilde{\rho}(\tilde{\theta}) d\tilde{\theta} \\ &= \int_{\theta \in A} \tilde{\rho}(\mathcal{T}(\theta)) |\nabla_{\theta}\mathcal{T}(\theta)| d\theta \end{aligned}$$

$$\mathcal{T}^{-1}: \tilde{\theta} \rightarrow \theta = \mathcal{T}^{-1}(\tilde{\theta})$$

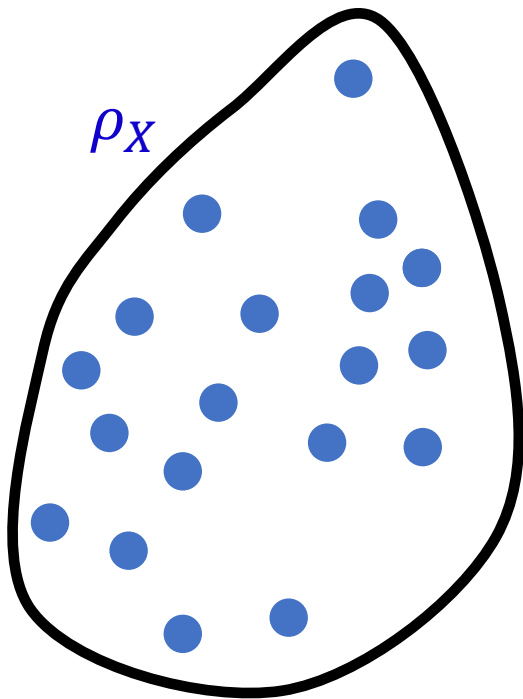
$$\mathcal{T}^{-1}: \tilde{\rho} \rightarrow \rho = \mathcal{T}^{-1}\#\tilde{\rho} \quad \tilde{\rho}(\tilde{\theta}) = \rho(\mathcal{T}^{-1}(\tilde{\theta}))|\nabla_{\tilde{\theta}}\mathcal{T}^{-1}(\tilde{\theta})|$$



# 标准化流

## ➤ 诱导测度

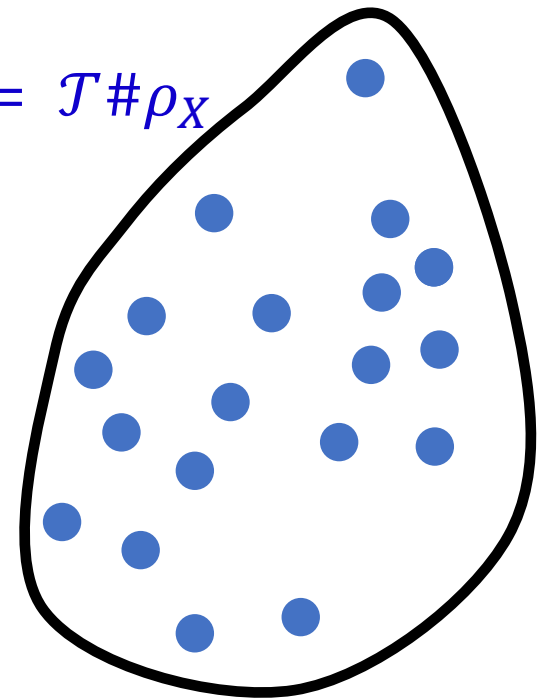
$$T: X \rightarrow Y$$



概率密度空间  $\mathcal{P}_X$



$$\rho_Y = T\#\rho_X$$



概率密度空间  $\mathcal{P}_Y$

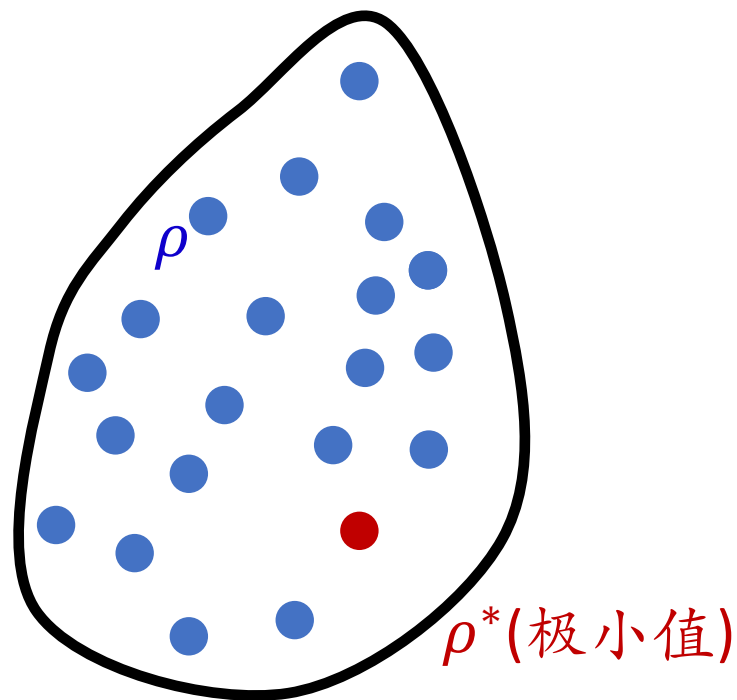


# 标准化流

## ➤ KL-散度

$$\text{KL}[\rho \parallel \rho^*] = \int \rho \log \left( \frac{\rho}{\rho^*} \right) d\theta$$

- $\text{KL}[\rho^* \parallel \rho^*] = 0$
- $\text{KL}[\rho \parallel \rho^*] \geq 0$
- $\text{KL}(\rho \parallel Z\rho^*) = \text{KL}(\rho \parallel \rho^*) - \log(Z)$



概率密度空间  $\mathcal{P}$



# 标准化流

## ➤ 标准化流

训练神经网络  $\mathcal{T}_{NN}$ :  $\{\theta^j\} \sim \rho_{\text{prior}} \rightarrow \{\mathcal{T}_{NN}(\theta^j)\} \sim \rho^*$

$$\begin{aligned} & \min_{NN} \text{KL}[\mathcal{T}_{NN}\#\rho_{\text{prior}} \parallel \rho^*] \\ & = \min_{NN} \int \mathcal{T}_{NN}\#\rho_{\text{prior}} (\log(\mathcal{T}_{NN}\#\rho_{\text{prior}}) + \Phi_R(\theta)) d\theta \end{aligned}$$

采样:  $\tilde{\theta}^j = \mathcal{T}_{NN}(\theta^j) \sim \mathcal{T}_{NN}\#\rho_{\text{prior}}$

计算目标函数, 更新神经网络

$$\begin{aligned} & \int \mathcal{T}_{NN}\#\rho_{\text{prior}} (\log(\mathcal{T}_{NN}\#\rho_{\text{prior}}) + \Phi_R(\theta)) d\theta \approx \\ & \frac{1}{J} \sum_{j=1}^J \log(\rho_{\text{prior}}(\theta^j) |\nabla_{\tilde{\theta}} \mathcal{T}_{NN}^{-1}(\tilde{\theta}^j)|) + \Phi_R(\tilde{\theta}^j) \end{aligned}$$





# 标准化流

## ➤ 标准化流

神经网络设计，计算  $\nabla_{\theta} \mathcal{J}_{NN}^{-1}(\tilde{\theta}^j)$

映射可逆、容易计算关于输入的导数

## ➤ 实值非体积保持模型

$$\mathcal{J}_{NN} = f_K \circ f_{K-1} \circ \cdots \circ f_1$$

$f_i$  包含仿射耦合层：

$$\begin{aligned} y_{1:d} &= x_{1:d} \\ y_{d+1:N_{\theta}} &= x_{d+1:N_{\theta}} \odot \exp(s(x_{1:d})) + t(x_{1:d}) \end{aligned}$$

随机打乱维度： $y_{1:N_{\theta}} \rightarrow y_{i_1:i_{N_{\theta}}}$



# 生成模型 (Generative model)

➤ 有未知归一化常数的目标分布

$$\rho^*(\theta) = \frac{1}{Z} e^{-\Phi_R(\theta)}$$

➤ 生成模型

已知： $\{\theta_j^{\text{data}}\} \sim \rho^*(\theta)$

生成： $\{\theta_j\} \sim \rho^*(\theta)$



# 扩展阅读

## ➤ 重要性采样

迭代的思路: Beskos, Alexandros, et al. "Sequential Monte Carlo methods for Bayesian elliptic inverse problems." *Statistics and Computing* 25 (2015): 727–737.

## ➤ 卡尔曼方法

无迹卡尔曼方法参数的选取。

第四种卡尔曼方法: Arasaratnam, Ienkaran, and Simon Haykin. "Cubature kalman filters." *IEEE Transactions on automatic control* 54.6 (2009): 1254-1269.

迭代的思路: Huang, Daniel Zhengyu, et al. "Efficient derivative-free Bayesian inference for large-scale inverse problems." *Inverse Problems* 38.12 (2022): 125006.

## ➤ 基于非线性映射的输运方法

标准化流: Rezende, Danilo, and Shakir Mohamed. "Variational inference with normalizing flows." *International conference on machine learning*. PMLR, 2015.

下三角映射: Marzouk, Youssef, et al. "An introduction to Sampling via measure transport." *Handbook of uncertainty quantification* 1 (2016): 2.