


- Perelman's Ricci flow theory

§1. Introduction.

- Poincaré Conjecture Every closed, smooth, simply connected

3-mfd is diffeomorphic to S^3 . #

- Rmk: In dim. 3, every homeomorphism can be approximated by diffeomorphisms.

- More general, we have:

- 3-dim. Space Form Conjecture Let M be a closed, connected 3-manifold,

and suppose that the fundamental group of M is a free product of finite groups and infinite cyclic groups. Then: M is diffeomorphic to spherical space forms, copies of $S^2 \times S^1$ or $S^2 \tilde{\times} S^1$, or a connect sum of them. #

- The proof depends on the following long-time existence result for Ricci flow with surgery.

- Theorem (Perelman). • (M, g_0) : closed Riem. 3-manifold.

- Suppose there is no embedded, locally separating IRP^2 contained in M .



- Then, there is a Ricci flow with surgery defined for all $t \in [0, +\infty)$, with initial metric (M, g_0) .
- The set of discontinuity times for this Ricci flow with surgery is a discrete subset of $[0, +\infty)$.
- Topological change in the 3-manifold when we cross a surgery time:
 - do connect sum decomposition
 - removal of connected components diffeomorphic to:
Spherical space forms, $S^2 \times S^1$, $S^2 \times S^1$, $IRP^3 \# IRP^3$. #
- For conjectures here, we don't need to analyze the nature of the flow as $t \rightarrow +\infty$.
- Theorem (Perelman). • M : closed 3-manifold.
- Assume $\pi_1(M)$ is a free product of finite groups and infinite cyclic group.
- Then: for any Riem. metric g_0 on M , the Ricci flow with surgery start with g_0 in the above form becomes extinct after some time $T < +\infty$, i.e., $M_t = \emptyset$ for all $t \geq T$. #
- Picture here:

Starting with (M, g_0) , we have a seq. of Ricci flows:

$$(M_1, (g_1^{(k)})_{t \in [0, T_1]}), (M_2, (g_2^{(k)})_{t \in [T_1, T_2]}), \dots$$

with $[0, +\infty) = [0, T_1] \cup [T_1, T_2] \cup \dots \cup [T_k, T_{k+1}] \cup \dots$, and

$$(M_i, g_i(T_i)) \xrightarrow{\text{surgery process}} (M_{i+1}, g_{i+1}(T_i))$$

If $M_k = \emptyset$, then M_0 is connect sum of

Spherical space forms, $S^2 \times S^1$, $S^2 \tilde{\times} S^1$, $\text{RP}^3 \# \text{RP}^3$.

• §2. Perelman's space-time geometry (L-geometry).

• (M, G) = n-dim. generalized Ricci flow (locally Ricci flow).

e.g.: $M = M \times [0, T]$, $G(t) = g(t)$, $\frac{\partial}{\partial t} g(t) = -2 \text{Ric}(g(t))$.

• Def. (Space-time curve). $t \uparrow$, $\tau = T - t \downarrow$.

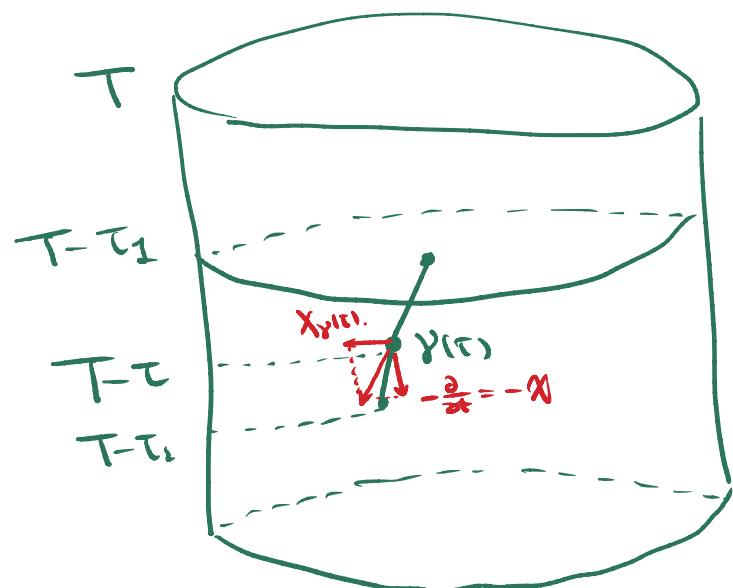
• $0 \leq \tau_1 < \tau_2$, $\gamma: [\tau_1, \tau_2] \rightarrow M$ be a continuous map, is called a space-time curve.

• γ is called parameterized by backward time, if:

$$\gamma(\tau) \in M_{T-\tau}, \quad \tau \in [\tau_1, \tau_2].$$

• Def. • $\gamma: [\tau_1, \tau_2] \rightarrow M$, a C^1 -path parametrized by backward time.

• $\frac{d\gamma}{d\tau} = -X + X_{\gamma(\tau)}$, $X_{\gamma(\tau)} \in T_{\gamma(\tau)} M$ is the horizontal component.



or write:

$$\gamma(\tau) = (\tilde{\gamma}(\tau), T-\tau).$$

then: $\frac{d\gamma}{d\tau} = \begin{pmatrix} \dot{\tilde{\gamma}}(\tau) \\ X_{\gamma(\tau)} \end{pmatrix}, \begin{pmatrix} -1 \\ -\infty \end{pmatrix}.$

- The L -length of γ is defined by:

$$L(\gamma) = \int_{T_1}^{T_2} \sqrt{\gamma \cdot \left(R(\gamma(\tau)) + |X_{\gamma(\tau)}|^2_{G_{T-\tau}} \right)} d\tau.$$

- Space parametrization: $s := \sqrt{\tau}$, $A(s) :=$ horizontal component of $\frac{d\gamma}{ds}$, then:

$$A(s) = 2s \cdot X(s^2), \quad L(\gamma) = \int_{\sqrt{T_1}}^{\sqrt{T_2}} \left(2 \cdot R(\gamma(s)) \cdot s^2 + \frac{1}{2} \cdot |A(s)|^2_{G_{T-s^2}} \right) ds.$$

- L -geodesics: critical points of L -functional.

- Euler-Lagrange equation (L -geodesic equation):

$$\nabla_X X - \frac{1}{2} \cdot \nabla R + \frac{1}{2\tau} \cdot X + 2 \operatorname{Ric}(X, \cdot)^* = 0.$$

- Def. An L -geodesic is said to be minimizing, if there is no curve parametrized by backward time, with the same endpoints and smaller L -length.

- Consider a family $\gamma(\tau, u)$ of L -geodesics parametrized by u and $\tau \in [\tau_1, \tau_2]$.

then: $\dot{Y}(\tau) := \frac{\partial}{\partial u} \gamma(\tau, u) \Big|_{u=0}$ satisfies the L -Jacobi equation.

$$\text{Jac}(Y) := \nabla_X \nabla_X Y + R(Y, X)X - \frac{1}{2} \nabla_Y (\nabla R) + \frac{1}{2\tau} \cdot \nabla_X Y \\ + 2(R_Y Ric)(X, \cdot)^* + 2\text{Ric}(\nabla_X Y, \cdot)^* = 0.$$

↑
2nd order

• If $\tau_1 > 0$, then $\exists!$ solution Y along γ solve this eqn, with $Y(\tau_1) = 0$,

$\nabla_X Y(\tau_1)$ is given; similar for τ_2 . ($\tau_1 = 0$, $\lim_{\tau \rightarrow 0} \sqrt{\tau} \cdot \nabla_X Y$).

• Proposition • γ minimizing L -geodesic, $\tau \in [\tau_1, \tau_2]$.

• Y : vector field along γ s.t. $Y(\tau_1) = Y(\tau_2) = 0$

• $\gamma_u(\tau) = \gamma(\tau, u)$: family of curves parameterized by backward time.

• $\frac{\partial}{\partial u} \gamma_u(\tau) \Big|_{u=0} = Y(\tau)$.

Then:

$$\frac{d^2}{du^2} L(\gamma_u) \Big|_{u=0} = - \int_{\tau_1}^{\tau_2} 2\sqrt{\tau} \langle \text{Jac}(Y), Y \rangle d\tau \geq 0.$$

• This quantity vanishes iff Y is a L -Jacobi field. #

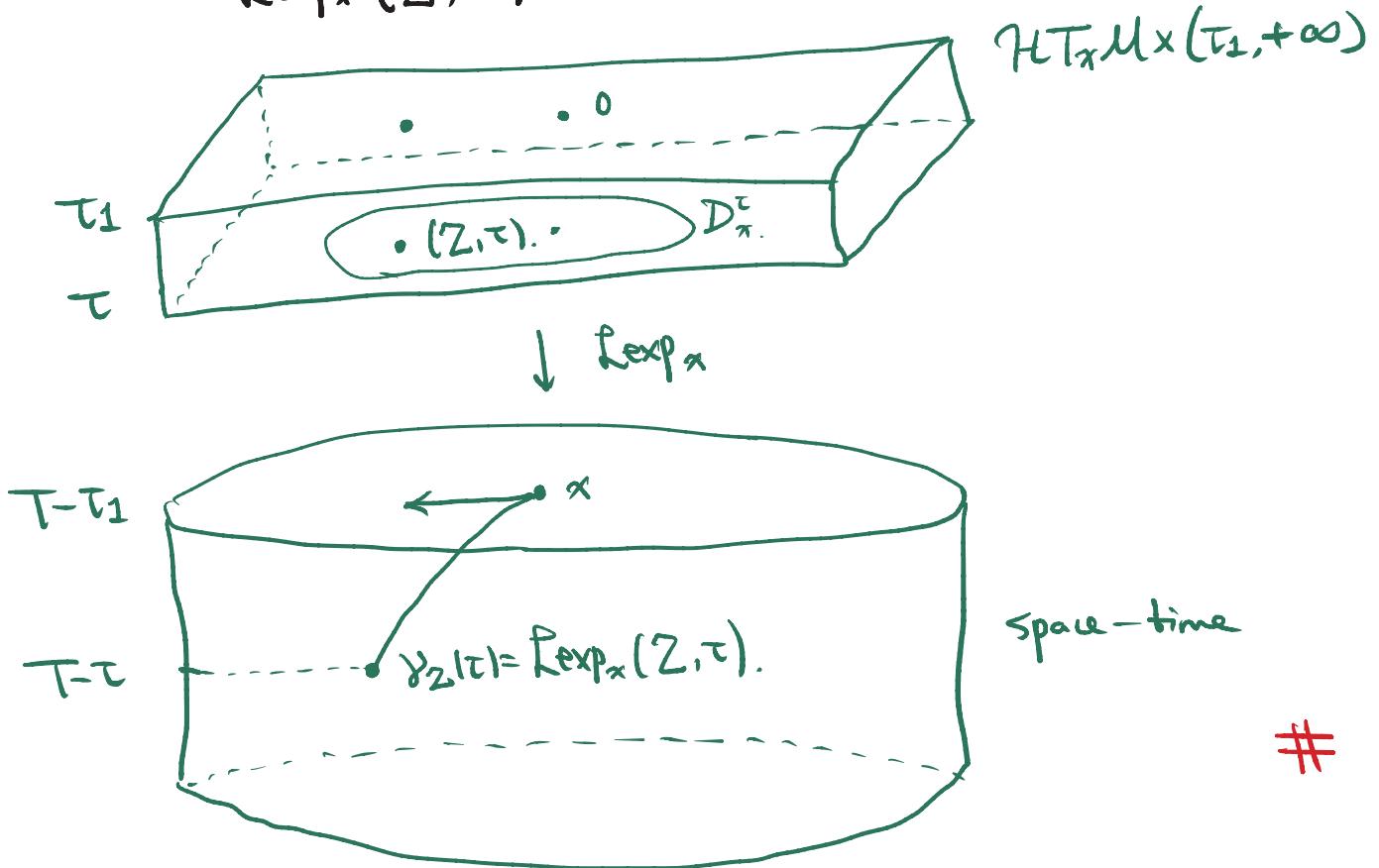
• Fix $\tau_1 > 0$, $x \in M$ with $\vec{f}(x) = \tau - \tau_1$. Then $\forall Z \in T_x M_{\tau - \tau_1} \exists$ a maximal L -geodesic γ_Z , defined on some $[\tau_1, \tau_2]$, $\tau_2 \leq +\infty$, with:

$$\gamma_Z(\tau_1) = x, \quad \sqrt{\tau_1} \cdot X(\tau_1) = Z. \quad (\text{If } \tau_1 = 0, \lim_{\tau \rightarrow 0} \sqrt{\tau} \cdot X(\tau) = Z).$$

- Def. • the domain of the def. of Lexp_x^τ , denoted by D_x , to be:
 $(Z, \tau) \in T_x M_{T-T_1} \times (\tau_1, +\infty)$, s.t. τ is in the maximal domain of γ_2 .

- Then we define: $\text{Lexp}_x: D_x \rightarrow M$ by:

$$\text{Lexp}_x(Z, \tau) = \gamma_Z(\tau).$$



- $\tilde{\mathcal{U}}_x \subseteq D_x$: injectivity domain. $\mathcal{U}_x := \text{Lexp}_x(\tilde{\mathcal{U}}_x) \subseteq M$.

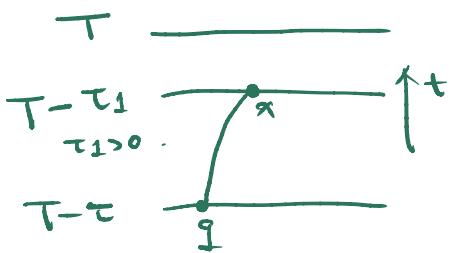
- Assume $|Rm| \leq C$ globally: \mathcal{U}_x open dense and has full measure, we have

smooth inequalities on \mathcal{U}_x , and weak inequalities globally.

- Def. $L_x: \mathcal{U}_x \rightarrow \mathbb{R}$, assigns to each $g \in \mathcal{U}_x$ the L -length of the minimizing L -geodesic from x to g .

• Def. • We define the τ -reduced length from x by:

$$l_x(\varrho) := \frac{L_x(\varrho)}{2\sqrt{\tau}} : \mathcal{U}_x \rightarrow \mathbb{R}$$



where $\tau = T - t(\varrho)$.

• R.K. l_x is easier to work with since it is scale invariant when $\tau_1 = 0$,

• Per. $K(x, t; y, s) \geq \frac{1}{(4\pi(t-s))^{\frac{n}{2}}} \cdot e^{-l_{(x,t)}(y,s)} \sim \frac{d_s^2(x, y)}{t-s}$

• Theorem (Perelman). Assume $x \in M_T$ (i.e., $\tau_1 = 0$). Then for $\varrho \in \mathcal{U}_x^\varepsilon$:

$$\textcircled{1} \quad \frac{\partial l_x}{\partial \tau}(\varrho) + \Delta l_x^\tau(\varrho) - \frac{\boxed{\frac{n}{2}} - l_x^\tau(\varrho)}{\tau} \leq 0.$$

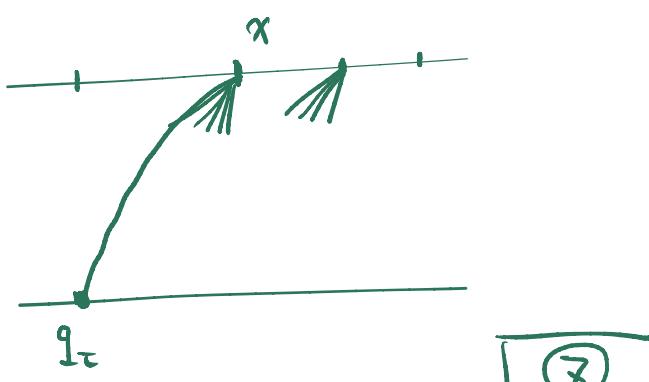
$$\textcircled{2} \quad \frac{\partial l_x}{\partial \tau}(\varrho) - \Delta l_x^\tau(\varrho) + |\nabla l_x^\tau(\varrho)|^2 - R(\varrho) + \frac{n}{2\tau} \geq 0$$

$$\textcircled{3} \quad \uparrow \quad 2\Delta l_x^\tau(\varrho) - |\nabla l_x^\tau(\varrho)|^2 + R(\varrho) + \frac{l_x^\tau(\varrho) - n}{\tau} \leq 0. \quad \#$$

• Globally, $\textcircled{1}$ is true in the barrier sense. This leads to:

$\forall 0 < \tau < T, \exists \varrho_\tau \in M \times \{T - \tau\}$, s.t.

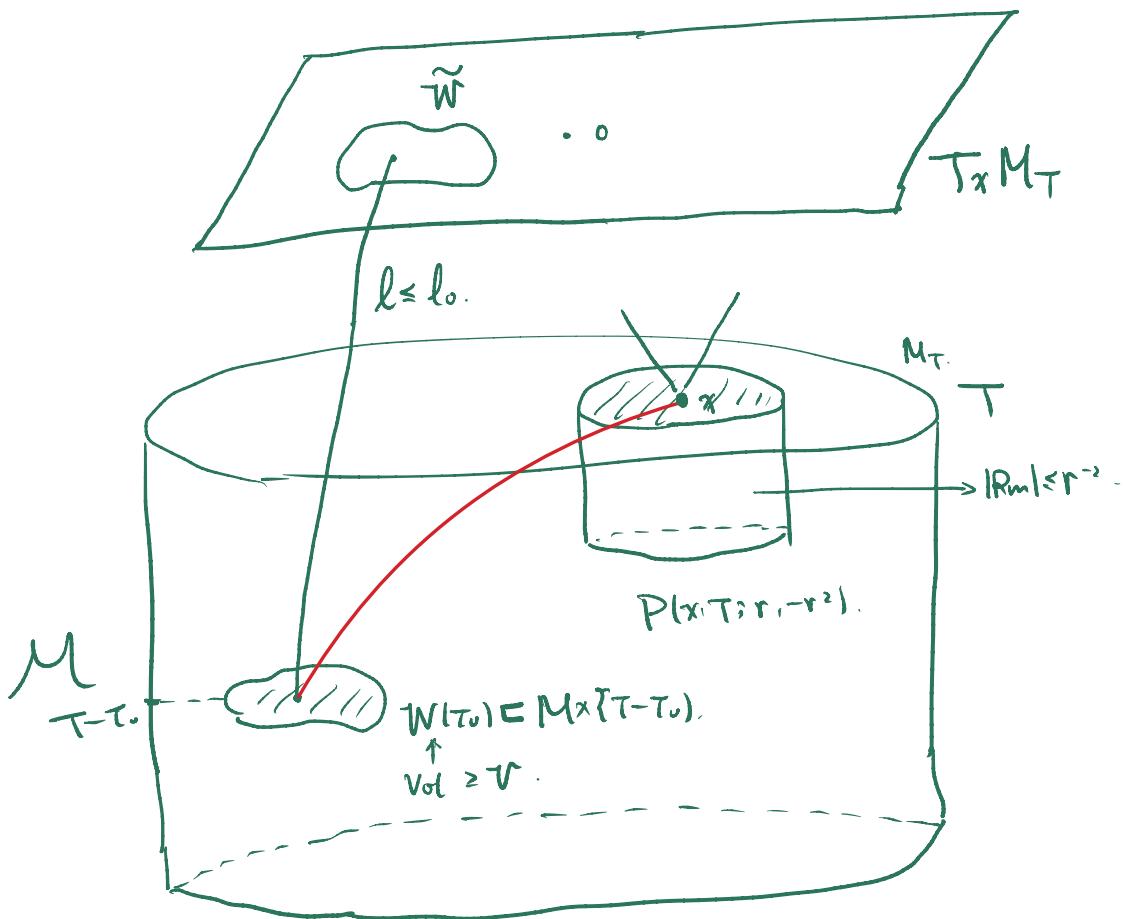
$$l_x(\varrho_\tau, \tau) \leq \frac{n}{2}.$$



- Theorem (Non-collapsing) • Given $\bar{T}_0 < +\infty$, $l_0 < +\infty$, $V > 0$
- \exists const. $K > 0$, depending on \bar{T}_0 , l_0 , V , n , s.t. the follo^g holds:
- (M, G) : generalized RF, n -dim, $0 < T_0 \leq \bar{T}_0$,
- $x \in M_{T_0}$, $0 < r \leq \sqrt{T_0}$. are given. Assume =
 - (1). $B(x, T, r) \subset M_T$ has compact closure
 - (2). \exists an embedding $P(x, T; r, -r^2) \subset M$ compatible with time and vector field.
 - (3). $|Rm| \leq r^{-2}$, on $P(x, T; r, -r^2)$.
- ★ (4). \exists an open subset $\tilde{W} = \bigcup_{x \in \tilde{W}} U_x(T_0) \subset T_x M_T$, s.t.: $\forall Z \in \tilde{W}$, let $\gamma_Z: [0, \tau] \rightarrow M$ be \mathbb{L} -geodesic with initial value Z , then: $l(\gamma_Z) \leq l_0$.
- ★ (5). For each $\tau \in (0, T_0]$, let $W(\tau) := \text{Lexp}_x^\tau(\tilde{W})$, then:

$$\text{Vol}_{g(T-T_0)}(W(T_0)) \geq V.$$
- Then:

$$\text{Vol}_{g(T)}(B(x, T, r)) \geq K \cdot r^n.$$



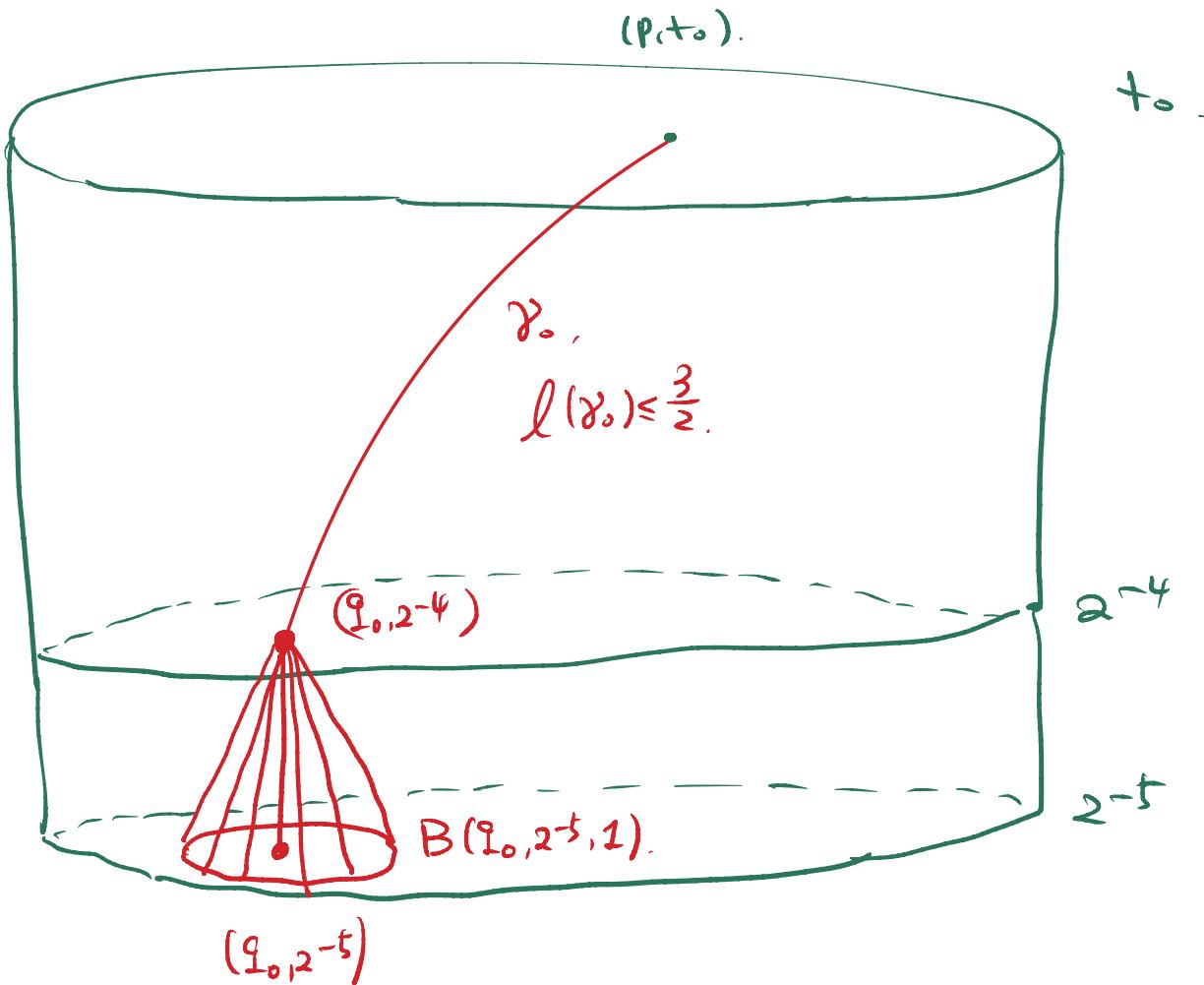
- Good example for general paradigm.
- Theorem. Fix $V_0 > 0$, $T_0 < +\infty$, $\exists K = K(V_0, T_0) \geq 0$, s.t.
- (M, g_{H^t}) , $0 \leq t \leq T \leq T_0$, 3-dim RF on cpt mfd M .
- Assume $|Rm|_{(p, 0)} \leq 1$. $Vol_{g_{(0)}}(B(p, 0, 1)) \geq V_0$, for all $p \in M$.
- Then: If $t_0 \leq T$, $r > 0$ with $r^2 \leq t_0$, $(p, t_0) \in M \times \{t_0\}$, if:

$|Rm| \leq r^{-2}$ on $P(p, t_0; r, -r^2)$,

\Downarrow K -non-collapsed

then:

$$Vol_{g_{(t_0)}}(B(p, t_0, r)) \geq K \cdot r^3.$$



• §3. Classification of gradient shrinking soliton.

- Fix $k > 0$. $t \in (-\infty, 0]$, complete, non-flat, $Rm \geq 0$. k -non-collapsed.
- (M, g_{t+1}) , $-\infty < t \leq 0$, n -dim. $\overset{\uparrow}{k}$ -solution.
- Fix $p \in M$, $x = (p, 0) \in M \times [-\infty, 0]$.
- $\forall \bar{\tau} > 0$, \exists a point $q_{\bar{\tau}} \in M$ s.t. $\ell_x(q_{\bar{\tau}}, \bar{\tau}) \leq \frac{n}{2}$.
- For $\bar{\tau} > 0$, define blow-down.

$$g_{\bar{\tau}}(t) := \frac{1}{\bar{\tau}} \cdot g(\bar{\tau} \cdot t), \quad -\infty < t \leq 0,$$
 $t = -1$ for $g_{\bar{\tau}}$
 \Downarrow
 $t = -\bar{\tau}$ for g .

Theorem • Let $\{\bar{\tau}_k\}_{k=1}^{\infty}$ satisfies $\bar{\tau}_k \rightarrow +\infty$ as $k \rightarrow +\infty$.

• Passing to a subseq., we have =

• For each $k \in \mathbb{N}^+$, consider $(M_k, g_k(t), (g_k, -1))$, $-\infty < t \leq 0$,

$$M_k = M, \quad g_k(t) = \bar{g}_{\bar{\tau}_k}(t), \quad I_k = I_{\bar{\tau}_k}$$

we have.

blow-down limit.

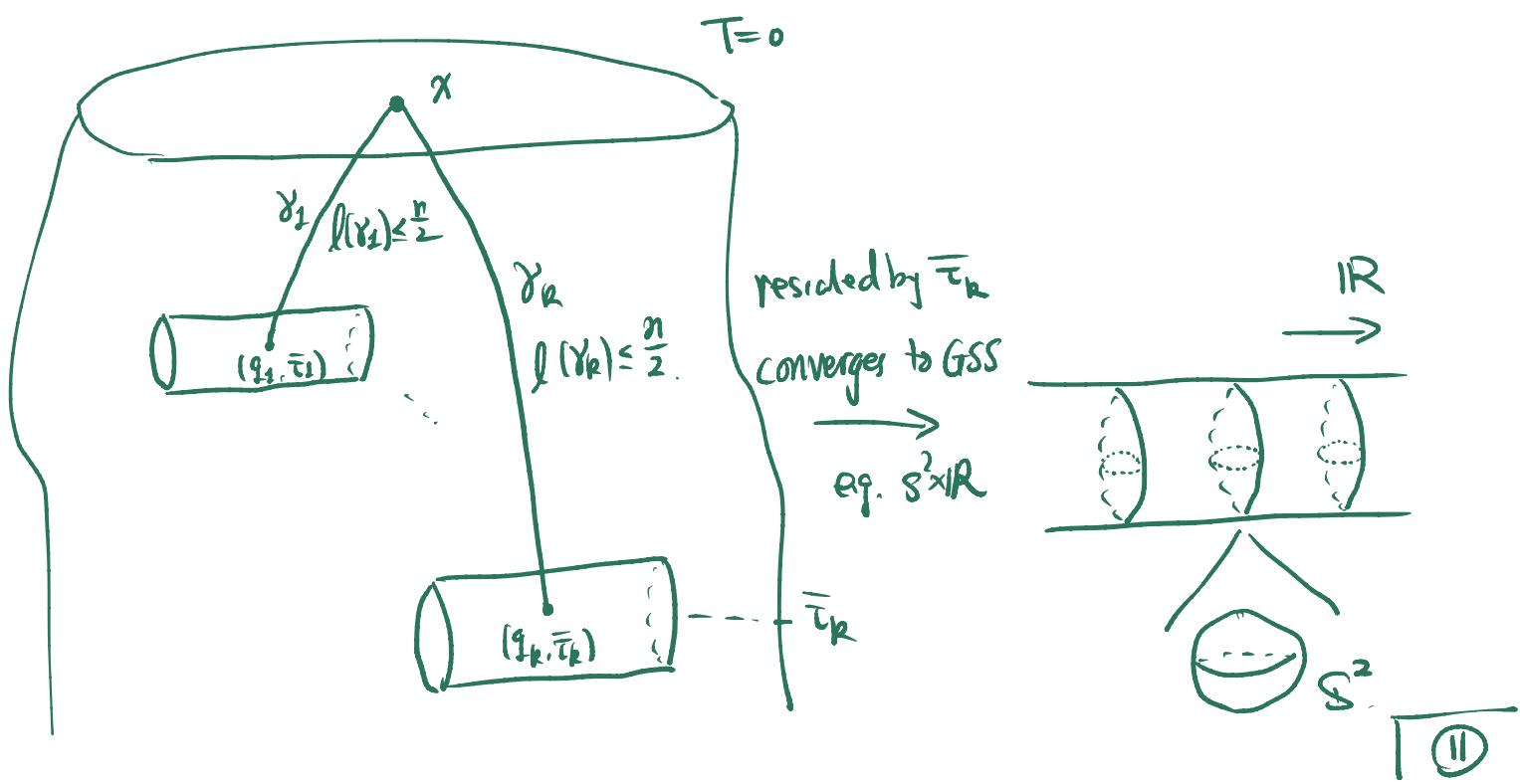
$$(M_k, g_k(t), (g_k, -1)) \xrightarrow[t \in (-\infty, 0)]{(-\text{-Cheeger-Gromov})} (M_\infty, \bar{g}_\infty(t), (g_\infty, -1))$$

• gradient shrinking soliton eqn.: $\exists f: M_\infty \times (-\infty, 0) \rightarrow \mathbb{R}$, smooth, s.t.

$$\text{Ric}_{g_\infty(t)} + \text{Hess}^{g_\infty(t)} f(t) + \frac{1}{2t} \cdot \bar{g}_\infty(t) = 0.$$

• $(M_\infty, \bar{g}_\infty(t))$ has non-negative curvature operator is κ -non-collapsed,

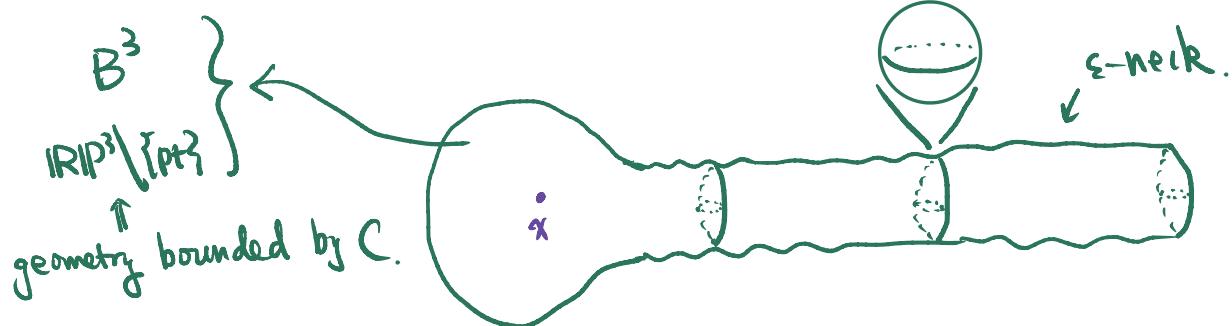
and satisfies $\partial R_{g_\infty(x,t)} / \partial t \geq 0$ for all $x \in M_\infty$, $t < 0$.



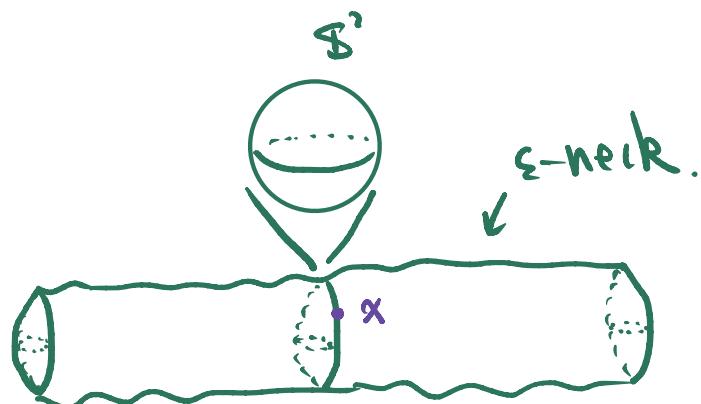
- In dim. 2, 3, we have the following classification:
- Theorem • (M, g) = complete, non-flat Riem. mfd of bounded, non-negative curvature of dim. 2 or 3.
- (M, g) is K -non-collapsed, for some $K > 0$.
- Suppose \exists a C^2 -function $f: M \rightarrow \mathbb{R}$ s.t.
$$Ric_g + \text{Hess}^g(f) = \frac{1}{2}g,$$
- Then: \exists a Ricci flow $(M, G(t))$, $-\infty < t < 0$, with $G(-1) = f$, and $(M, G(t))$ is isometric to $(M, 1+t \cdot g)$ for every $t < 0$.
- In addition, $(M, G(t))$ is one of the following three types:
 - (1). The flow $(M, G(t))$, $-\infty < t < 0$, is a shrinking family of compact, round (constant positive curvature) mfds. ($S^2, S^3, \text{RP}^2, \text{RP}^3$)
 - (2). The flow $(M, G(t))$, $-\infty < t < 0$, is a product of a shrinking family of 2-surfaces with (\mathbb{R}, ds^2) .
 \uparrow
 S^2, RP^2
 - (3). Quotient of $S^2 \times \mathbb{R}$ in (2) under involution map ι .

• §4. Canonical nbhds. (nbhd of singularities).

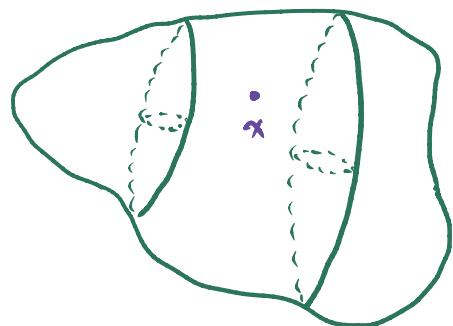
(1). (C, ε) -cap:



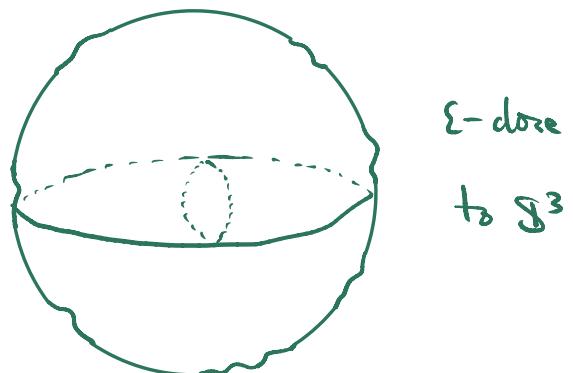
(2). ε -neck.



(3). C -component:



(4). ε -round



- (C, ε) -canonical assumption: For a function $r(t) \rightarrow 0^+$ as $t \rightarrow +\infty$, for any $(x, t) \in M$ with $R(x, t) \geq r(t)^{-2}$, (x, t) has a (C, ε) -nbhd.
- Need to show: this assumption stays true if we construct the Ricci flow with surgery in suitable way.

- With (C, ε) -canonical nbhd assumption, we can apply:

- Theorem. (Bounded curvature at bounded distance).

- Fix $\varepsilon > 0$, $C < +\infty$, $A < +\infty$.

- $\exists D_0 < +\infty$, $D < +\infty$, depending on ε, C, A , s.t.:

- Assume (M, G) is a generalized RF with $t \in [0, +\infty)$, $x \in M$, with:

- (1). (M, G) has curvature pinched toward positive.

- (2). For every $y \in M$ with $R(y) \geq 4R(x)$ and $t(y) \leq t(x)$,

y has a (C, ε) -canonical nbhd.

contradiction argument to

- Then: if $R(x) \geq D_0$, then:

$$R(y) \leq D \cdot R(x), \text{ for all } y \in B(x, t, A \cdot R(x)^{-\frac{1}{2}}).$$

- Rmk: With this thm, we can apply Hamilton's compactness thm.

- About proof:

contradiction argument

to extract a non-flat

Gromov-Hausdorff limit

on a cone.

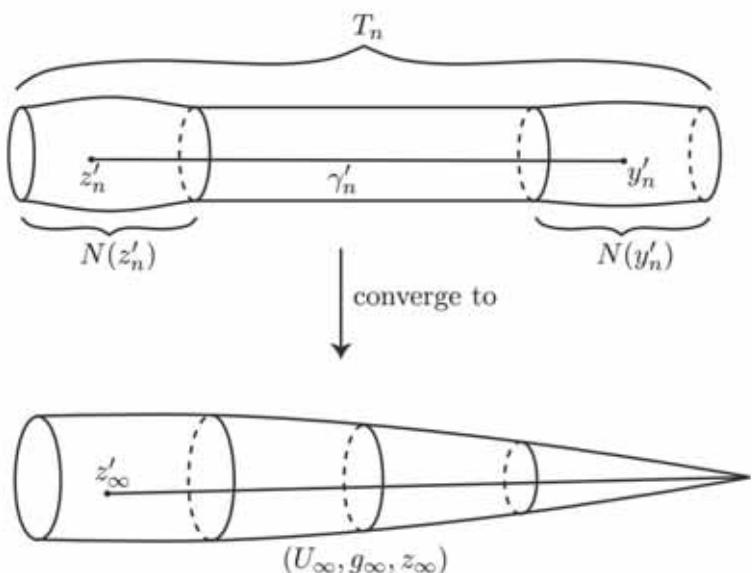
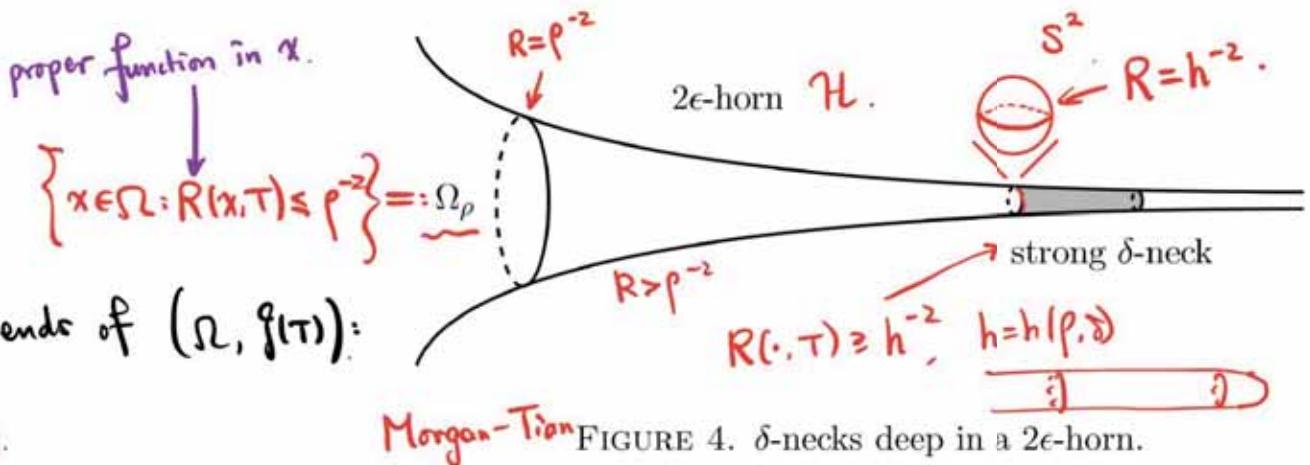


FIGURE 1. Limiting tube.

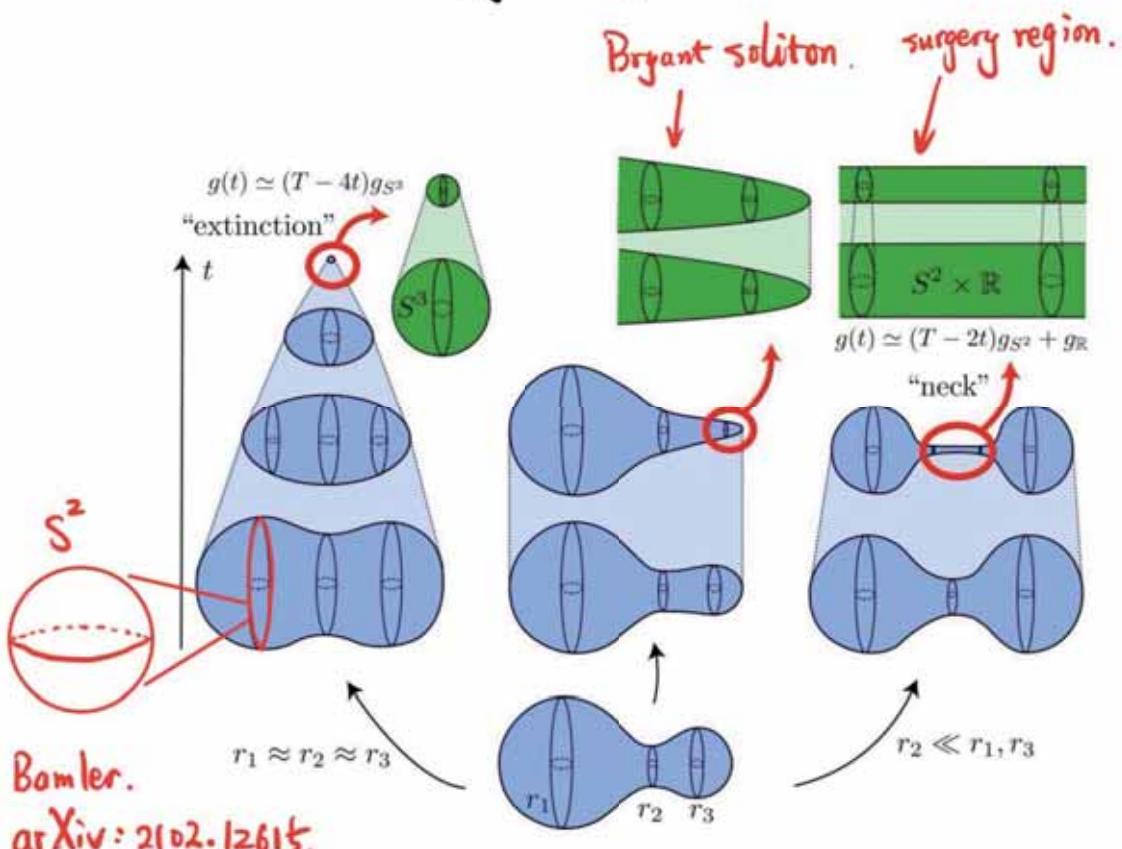
• Existence of δ -neck in non-trivial components.

• Define $\Omega := \{x \in M : \liminf_{t \uparrow T} R(x, t) < \infty\}$. $\stackrel{\text{open.}}{=} M$, then $g(t) \xrightarrow{C^\infty_{loc}(\Omega)} g(T)$



• Typical example. Ricci flow with rotational symmetry

Bryant soliton on \mathbb{R}^3 : $g_{Bry} = f^2(r) \cdot g_{S^2} + dr^2$, $f(r) \sim r^{\frac{1}{2}}$



• Standard solution: (gluing piece).

- Fix a non-negatively curved, rotationally symmetric metric on \mathbb{R}^3 , which is isometric near infinity to $S^2 \times [0, \infty)$, with round metric of $R=1$ on S^2 .

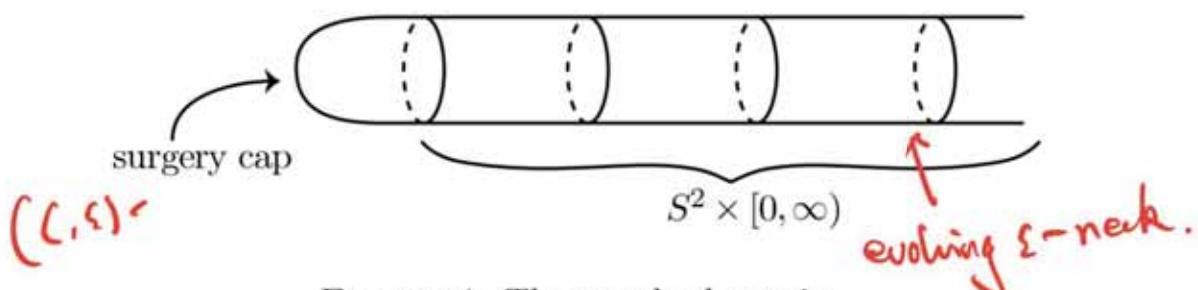
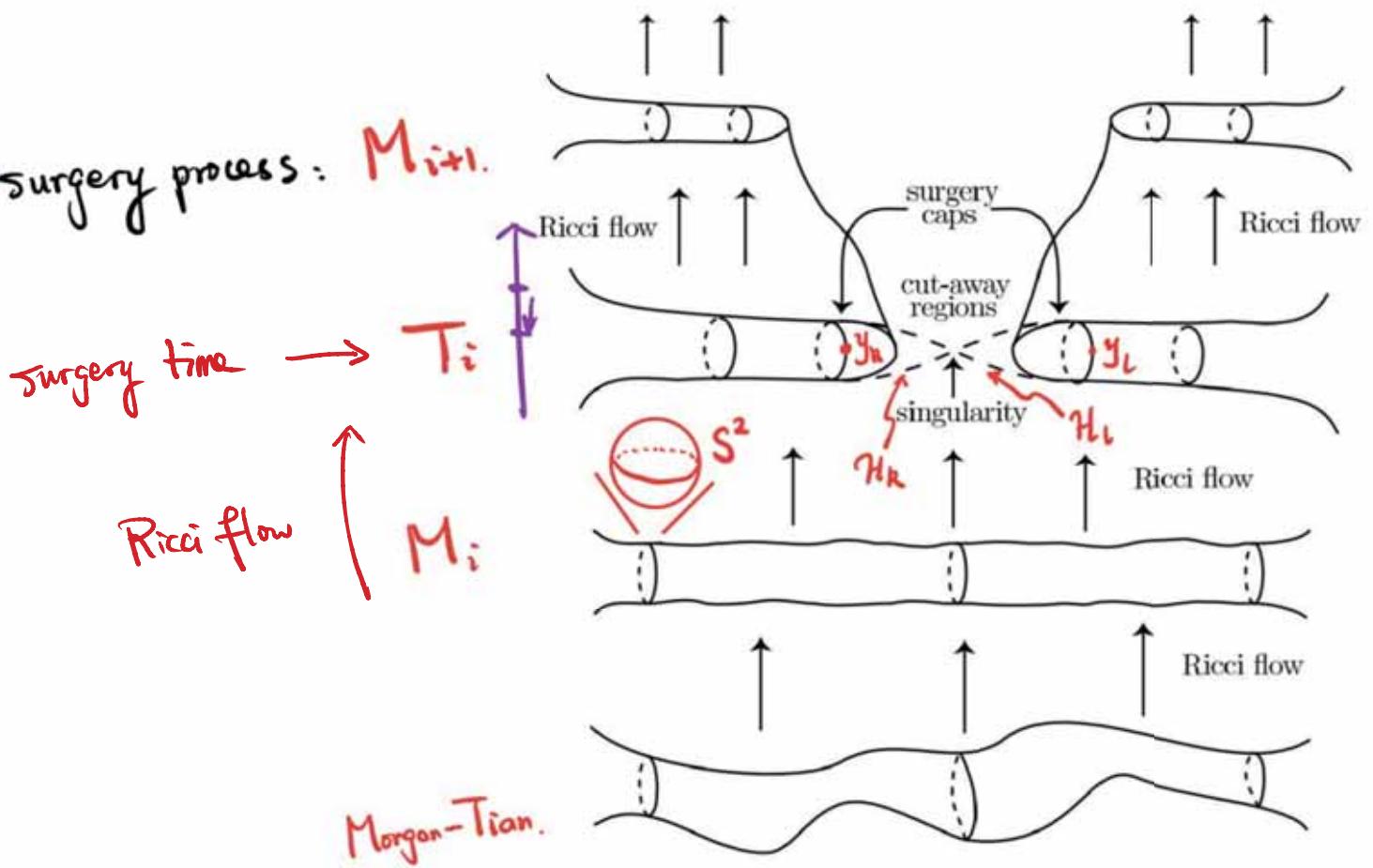


FIGURE 4. The standard metric.

• §5. Ricci flow with surgery.

• surgery process: M_{i+1} .

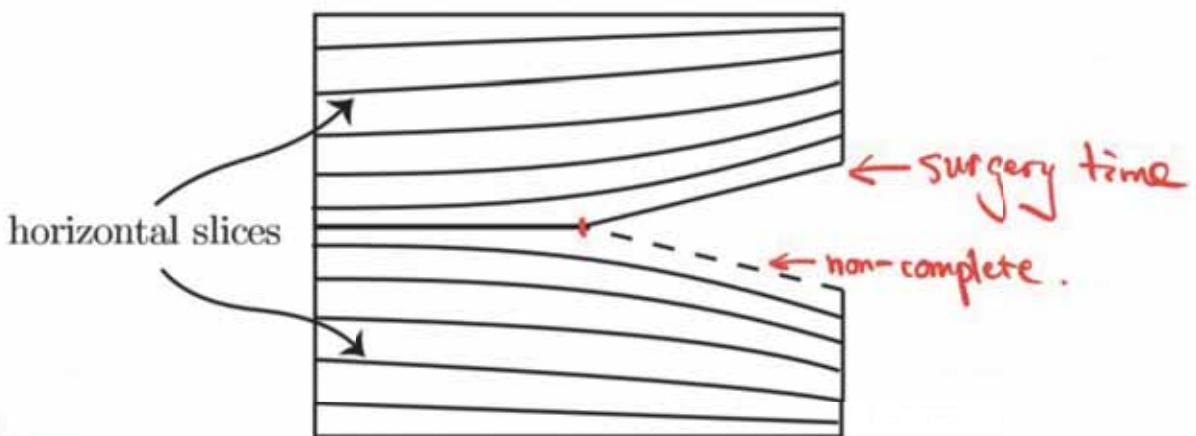


- A 3-dim. Ricci flow with surgery consists a sequence of Ricci flows:
 $(M_1, (g_{1(t)})_{t \in [0, T_1]})$, $(M_2, (g_{2(t)})_{t \in [T_1, T_2]})$,

with $[0, \infty) = [0, T_1] \cup [T_1, T_2] \cup \dots$, and

$$(M_i, g_i(T_i)) \xrightarrow{\text{surgery process}} (M_{i+1}, g_{i+1}(T_i))$$

- Find H_1, \dots, H_j the 2ϵ -horns as above, $h_i \ll \rho_i \ll r_i \rightarrow 0$.
 find $y_k \in H_k$ with $R(y_k) = h_i^{-2}$, cut the cross-sectional 2-spheres
 through y_k , glue in cap-shaped 3-disks to this cutting surface.



Morgan-Tian.

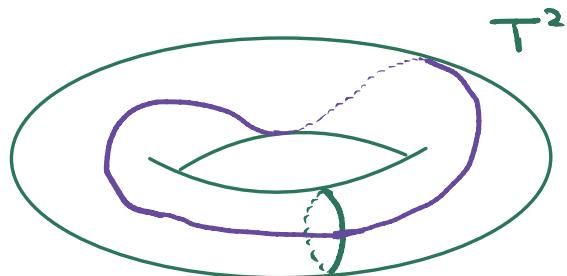
FIGURE 5. Model for singularities in space-time.

- This is a generalized Ricci flow.

• Inductive conditions:

- (1) curvature pinched toward positive.
- (2) R_i -non-collapsed on scale $\leq r_i$ of $(M_i, g_i(t))$, $T_{i-1} \leq t \leq T_i$.
- (3) (C, ϵ) -canonical neighborhood assumption.

- Why S^2 is important.
- Surgery along S^2 produces the connect sum decomposition.
- Dehn surgery along tori can destroy the topology.



- Perelman: Let (M, g) be a closed 3-mfd, if r_i are chosen sufficiently small, then:
- (1). the surgery times T_i do not accumulate.
 - (2). a Ricci flow with surgery with initial condition $(M_1, g_{1(0)}) = (M, g)$ can be constructed.
- Change in topology: for any i ,

$$M_1 \approx M_i \#_{j=1}^k (S^3/\Gamma_j) \# m (S^2 \times S^1)$$

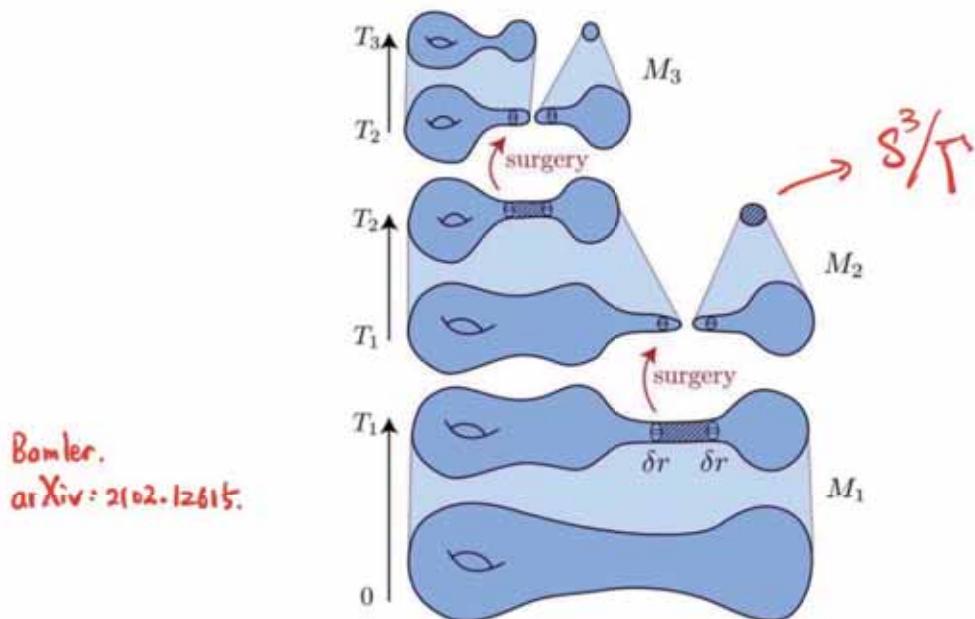


Figure 3: A schematic depiction of a Ricci flow with surgery. The almost-singular parts $M_{\text{almost-sing}}$, i.e. the parts that are discarded under each surgery construction, are hatched.

- Perelman: If M_i is simply connected, then the flow has to go extinct, i.e., $M_i = \emptyset$ for i large.

\Rightarrow Poincaré Conjecture:

Any closed, simply connected 3-manifold is diffeomorphic to S^3 .

- Idea of finite time extinction. (back to Hamilton)

- Define $W_2(t) : [0, \infty) \rightarrow \mathbb{R}_{\geq 0}$ by:

$W_2(t) = \text{minimal area of all homotopically non-trivial 2-sphere.}$

- Then in the weak sense,

$$\frac{dW_2(t)}{dt} \leq -4\pi + \frac{3}{(4t+1)} \cdot W_2(t). \quad \text{← pass surgery}$$

$\Rightarrow W_2(t) < 0$ for t large, a contradiction.

- Perelman: Analysis of the long time solution solves the Geometrization Conjecture.
- Ricci flow through singularities in dim. 3.
 - the surgery is not unique, depends on:
 - surgery scale.
 - surgery spheres.
- Conjecture (Perelman). As $r_i \rightarrow 0$ for each i , we will obtain some kind of canonical Ricci flow through singularities.
- Kleiner-Lott, Bamler-Kleiner proved this conjecture, and use this to prove the Generalized Smale Conjecture.