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• §4. 2nd variation formula, Jacobi fields. Space forms.

• §4.1. 2nd variation formula.

- Let  $\gamma: [0, l] \times (-\varepsilon, \varepsilon) \rightarrow M$  be a variation.
- Denote  $\gamma_u(t) := \gamma(t, u)$ .
- Assume  $\gamma_0$  is a unit speed geodesic.
- $X = \frac{\partial}{\partial t} \gamma$ ,  $Y = \frac{\partial}{\partial u} \gamma$ .

• Prop. 1. We have:

$$\frac{d^2}{du^2} L(\gamma_u) \Big|_{u=0} = \langle \nabla_Y Y, X \rangle \Big|_0 + \int_0^l \left[ |(\nabla_X Y)^{\perp}|^2 - R_m(X, Y, X, Y) \right] dt$$

where  $(\nabla_X Y)^{\perp} = \nabla_X Y - \langle \nabla_X Y, X \rangle \cdot X$ .

• Proof: • Recall:  $\nabla_X Y - \nabla_Y X = [X, Y] = 0$ .

• At  $u=0$ , we compute:

$$\begin{aligned} \frac{d^2}{du^2} L(\gamma_u) &= \frac{d}{du} \int_0^l \frac{Y \langle X, X \rangle}{2|X|} dt = \frac{d}{du} \int_0^l \frac{\langle \nabla_X Y, X \rangle}{|X|} dt \\ &= \int_0^l \left[ \frac{Y \langle \nabla_X Y, X \rangle}{|X|} - \frac{\langle \nabla_X Y, X \rangle \cdot \langle \nabla_X Y, X \rangle}{|X|^3} \right] dt. \end{aligned}$$

$$|X|=1 \quad = \int_0^l \left[ \langle \nabla_Y \nabla_X Y, X \rangle + \langle \nabla_X Y, \nabla_Y X \rangle - \langle \nabla_X Y, X \rangle^2 \right] dt.$$

• For the first term, we have:  $[X, Y] = 0 \Rightarrow R(X, Y)Y = \nabla_X \nabla_Y Y - \nabla_Y \nabla_X Y$ .



$$\begin{aligned}
\int_0^l \langle \nabla_Y \nabla_X Y, X \rangle dt &= \int_0^l \langle \nabla_X \nabla_Y Y, X \rangle - \langle R(X, Y)Y, X \rangle dt \\
&= \int_0^l X \underbrace{\frac{d}{dt} \langle \nabla_Y Y, X \rangle}_{\text{d}} dt - \int_0^l R_m(X, Y, X, Y) dt \\
&= \langle \nabla_Y Y, X \rangle \Big|_{t=0}^l - \int_0^l R_m(X, Y, X, Y) dt.
\end{aligned}$$

• Also, we have:

$$\langle \nabla_X Y, \nabla_X Y \rangle - \langle \nabla_X Y, X \rangle^2 = \left| \nabla_X Y - \langle \nabla_X Y, X \rangle \cdot X \right|^2 = \left| (\nabla_X Y)^{\perp} \right|^2.$$

\(\blacksquare\)

• Theorem 2. (Bonnet - Myers). •  $(M^n, g)$ : complete, connected.

•  $\text{Ric} \geq (n-1) K_0 \cdot g$ ,  $K_0 > 0$ , a constant.

• Then:  $\text{Diam}(M, g) := \sup \{ d(p, q) \mid p, q \in M \} \leq \frac{\pi}{\sqrt{K_0}}$

• Proof: • Let  $p, q \in M$  be any two points,  $l = d(p, q)$ .

• Since M is complete, we can find a minimal geodesic  $\gamma: [0, l] \rightarrow M$  with

$\gamma(0) = p$ ,  $\gamma(l) = q$ . then  $|\dot{\gamma}| = 1$ .

• At  $p = \gamma(0)$ , take  $\{e_1, \dots, e_{n-1}, e_n = \dot{\gamma}(0)\} \subset T_p M$  an orthonormal basis.

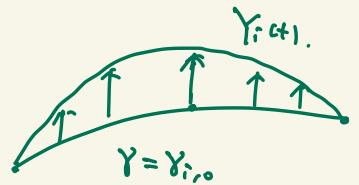
• Let  $e_i(t)$  be parallel translation of  $e_i$  along  $\gamma$ ,  $i = 1, \dots, n-1$ , i.e.,

$$\nabla_{\dot{\gamma}(t)} e_i(t) = 0, \quad e_i(0) = e_i. \quad (\text{ODE, } \exists! \text{ solution})$$

• Define variation fields  $Y_i(t) := \sin\left(\frac{\pi}{l} \cdot t\right) \cdot e_i(t)$ ,  $0 \leq t \leq l$ ,  $1 \leq i \leq n-1$ .

- For every  $1 \leq i \leq n-1$ ,  $\exists$  variation curves:

$$\gamma_{i,u}(t) = \gamma_i(t, u) := \exp_{\gamma_i(t)}(u \cdot Y_i(t)).$$



with  $\gamma = \gamma_{i,0}$ ,  $\frac{\partial}{\partial u}|_{u=0} \gamma_i = Y_i$ .

- Since  $\forall 1 \leq i \leq n-1$ ,  $\langle e_i(0), \dot{\gamma}(0) \rangle = 0$ , and

$$\frac{d}{dt} \langle e_i(t), \dot{\gamma}(t) \rangle = \langle \nabla_{\dot{\gamma}(t)} e_i(t), \dot{\gamma}(t) \rangle + \langle e_i(t), \nabla_{\dot{\gamma}(t)} \dot{\gamma}(t) \rangle = 0,$$

we have:  $\langle e_i(t), \dot{\gamma}(t) \rangle = 0$ ,  $t \in [0, l]$ . Hence:

$$\langle \nabla_{\dot{\gamma}(t)} Y_i(t), \dot{\gamma}(t) \rangle = \left\langle \frac{\pi}{l} \cdot \cos\left(\frac{\pi}{l} \cdot t\right) \cdot e_i(t) + \sin\left(\frac{\pi}{l} \cdot t\right) \cdot \nabla_{\dot{\gamma}(t)} e_i(t), \dot{\gamma}(t) \right\rangle \stackrel{!!}{=} 0$$

Hence  $(\nabla_{\dot{\gamma}(t)} Y_i)^{\perp} = \nabla_{\dot{\gamma}(t)} Y_i$ .

- Now, from Prop. 1,  $\forall 1 \leq i \leq n-1$ , since  $Y_i(0) = 0 = Y_i(l)$ , and

$\gamma_{i,0} = \gamma$  is minimal geodesic.

$$0 \leq \frac{d^2}{du^2} L(\gamma_{i,u}) \Big|_{u=0} = \int_0^l \left[ |\nabla_{\dot{\gamma}} Y_i|^2 - Rm(\dot{\gamma}, Y_i, \dot{\gamma}, Y_i) \right] dt$$

$$= \int_0^l \left[ \left( \frac{\pi}{l} \right)^2 \cdot \cos^2\left(\frac{\pi}{l} \cdot t\right) - \sin^2\left(\frac{\pi}{l} \cdot t\right) \cdot Rm(\dot{\gamma}, e_i, \dot{\gamma}, e_i) \right] dt$$

- Summing up  $1 \leq i \leq n-1$ ,

$$0 \leq \int_0^l \left[ (n-1) \cdot \left( \frac{\pi}{l} \right)^2 \cdot \cos^2\left(\frac{\pi}{l} \cdot t\right) - \sin^2\left(\frac{\pi}{l} \cdot t\right) \cdot \underbrace{\text{Ric}(\dot{\gamma}, \dot{\gamma})}_{\text{Ric} \geq (n-1) K_0 g}, |\dot{\gamma}| = 1 \right] dt$$

$$\leq \int_0^l \left[ (n-1) \cdot \left( \frac{\pi}{l} \right)^2 \cdot \cos^2\left(\frac{\pi}{l} \cdot t\right) - \sin^2\left(\frac{\pi}{l} \cdot t\right) \cdot (n-1) K_0 \right] dt$$

$$= (n-1) \cdot \left[ \left( \frac{\pi}{l} \right)^2 - K_0 \right] \cdot \int_0^l \sin^2 \left( \frac{\pi}{l} \cdot t \right) dt .$$

Hence:

$$\left( \frac{\pi}{l} \right)^2 - K_0 \geq 0 \quad \Rightarrow \quad l \leq \frac{\pi}{\sqrt{K_0}} .$$



### • Theorem 3. (Synge).

- $(M^{2n}, g)$ : sectional curvature = constant  $K_0 > 0$ , compact.
- If  $M$  is orientable, then  $M$  is simply connected. ( $\pi_1(M) = 0$ ).

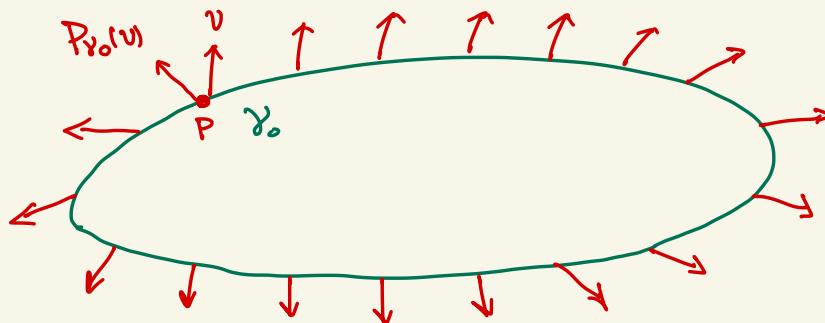
• Proof: Suppose  $\exists$  non-trivial homotopy class  $\alpha \in \pi_1(M)$ .

Then by compactness,  $\exists$  shortest representation  $\gamma_0 \in \alpha$ , a closed geodesic.

• Construct a parallel vector field  $Y$  along  $\gamma_0$ :

- Fix  $\gamma_0(0) = p \in M$ , consider parallel translation:

$$P_{\gamma_0}: T_p M \xrightarrow{\cong} T_p M, \quad P_{\gamma_0} \in SO(T_p M)$$



- Since  $\gamma_0$  is a geodesic,  $P_{\gamma_0}(\dot{\gamma}_0(0)) = \dot{\gamma}_0(0)$ . Hence:

$$P_{\gamma_0}: \dot{\gamma}_0(0)^\perp \longrightarrow \dot{\gamma}_0(0)^\perp$$

is an isomorphism. Here  $\dot{\gamma}_0(0)^\perp := \{v \in T_p M : \langle v, \dot{\gamma}_0(0) \rangle = 0\}$ .

- But  $\dim \dot{\gamma}_0(0)^\perp = 2n - 1$ , is odd, hence  $\exists$  fixed point  $0 \neq v \in \dot{\gamma}_0(0)^\perp$  of  $P_{\dot{\gamma}_0}$ , i.e.,  $v \neq 0$ ,  $P_{\dot{\gamma}_0}(v) = v$ .

Since  $M$  is orientable, and  $P_{\dot{\gamma}_0}(\dot{\gamma}_0(0)) = \dot{\gamma}_0(0)$ , hence

$P_{\dot{\gamma}_0} \in SO(\mathbb{R}^{2n})$  must have another eigenvalue = 1, whose eigenvector  $v (\neq 0)$  is another fixed point of  $P_{\dot{\gamma}_0}$ .

- Let  $Y(u)$  be the parallel vector field of  $v$  along  $\dot{\gamma}_0$ .
- Find variation curves  $Y_u(t) = \gamma(t, u)$  of  $Y(t)$ . (i.e.  $\frac{\partial}{\partial u}|_{u=0} Y = Y$ ).

Then from Prop.1 since  $\dot{\gamma}_0$  is a minimal geodesic,

$$0 \leq \frac{d^2}{du^2} \Big|_{u=0} L(Y_u) = \int_0^l \left[ |\nabla_{\dot{\gamma}_0} Y|^2 - Rm(\dot{\gamma}_0(t), Y(t), \dot{\gamma}_0(t), Y(t)) \right] dt$$

$\begin{matrix} |\dot{\gamma}_0|=1=|Y| \\ \langle \dot{\gamma}_0, Y \rangle = 0 \end{matrix} \quad \boxed{\quad}$

$$= - \int_0^l K_0 dt = - K_0 l < 0.$$



## • §4.2 Jacobi fields.

- Let  $\gamma: [0, l] \times (-\varepsilon, \varepsilon) \rightarrow M$  be a variation of geodesics, i.e., each  $\gamma_u(t) = \gamma(t, u)$  is a geodesic.
  - Let  $X = \frac{\partial}{\partial t} \gamma$ ,  $Y = \frac{\partial}{\partial u} \gamma$ ,  $[X, Y] = 0$ .
  - Then, since  $\gamma_u$  is a geodesic,  $\nabla_X X = 0$ , hence:
- $$0 = \nabla_Y \nabla_X X = \nabla_X \nabla_Y X - R(X, Y)X = \nabla_X \nabla_Y Y - R(X, Y)X.$$



• Def. 4. (Jacobi field). Let  $\gamma$  be a geodesic. A vector field  $J$  along  $\gamma$  is called a Jacobi field, if:

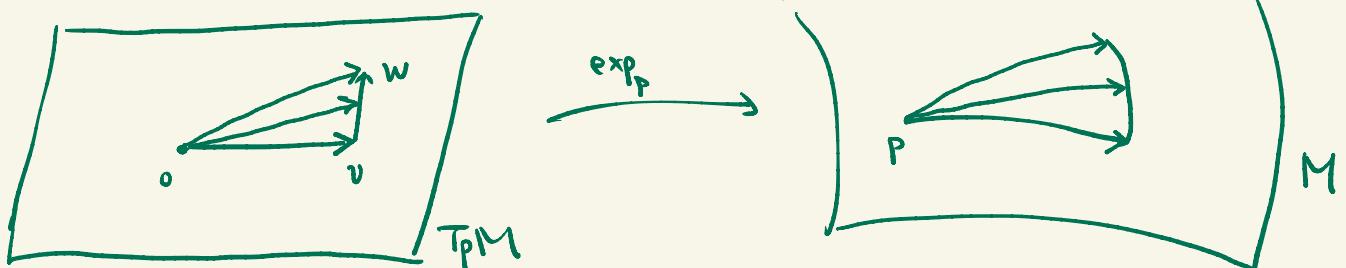
$$(1). \quad \nabla_{\dot{\gamma}} \nabla_{\dot{\gamma}} J - R(\dot{\gamma}, J) \dot{\gamma} = 0. \quad \#$$

- (1) is a 2nd order ODE along  $\gamma$ , it can be uniquely solved according to the initial value  $J(0)$  &  $J'(0) := \nabla_{\dot{\gamma}(0)} J(0)$ .

### • Construction of Jacobi field:

- Take  $v, w \in T_p M$ , let:

$$\gamma_{ut} := \gamma(t, u) := \exp_p(t \cdot (v + u \cdot w))$$



then  $J(t) = \frac{\partial}{\partial u} \Big|_{u=0} \gamma(t, u)$  is Jacobi field along  $\gamma$ .

- $\gamma_{u(0)} = p$ , fixed point  $\Rightarrow J(0) = 0$ .

- $J'(0) = \nabla_{\dot{\gamma}_{u(0)}} J(0) = w$ :

$$\nabla_{\dot{\gamma}_{u(t)}} J(t) = \nabla_{\dot{\gamma}_{u(t)}} \left[ d(\exp_p)_{t \cdot v} (+w) \right] = \nabla_{\dot{\gamma}_{u(t)}} \left[ t \cdot d(\exp_p)_{tv}(w) \right]$$

$$= d(\exp_p)_{tv}(w) + t \cdot \nabla_{\dot{\gamma}_{u(t)}} \left[ d(\exp_p)_{tv}(w) \right].$$

#

• Lemma 5: For any Jacobi field  $J$  along geodesic  $\gamma$ , we have:

$$\langle J, \dot{\gamma} \rangle(t) = \langle J, \dot{\gamma} \rangle(0) + \langle J', \dot{\gamma} \rangle(0) \cdot t.$$

Proof: • From the Jacobi eqn. (1), we have:

$$\frac{d^2}{dt^2} \langle J, \dot{\gamma} \rangle = \frac{d}{dt} \langle \nabla_{\dot{\gamma}} J, \dot{\gamma} \rangle = \langle \nabla_{\dot{\gamma}} \nabla_{\dot{\gamma}} J, \dot{\gamma} \rangle$$

$$\stackrel{(1)}{=} \langle R(\dot{\gamma}, J)\dot{\gamma}, \dot{\gamma} \rangle = R_m(\dot{\gamma}, J, \dot{\gamma}, \dot{\gamma}) \underset{\text{anti-symmetry of } R_m}{=} 0$$

anti-symmetry of  $R_m$

• Next, we have:

$$\left. \frac{d}{dt} \right|_{t=0} \langle J, \dot{\gamma} \rangle = \langle \nabla_{\dot{\gamma}} J, \dot{\gamma} \rangle(0).$$

□

- Note that  $(at+b) \cdot \dot{\gamma}(t)$  is always a Jacobi field,  $\forall a, b \in \mathbb{R}$ .
- From Lemma 5, any Jacobi field  $J$  admits a decomposition:

$$J = J^\perp + J''$$

where

$$\cdot J''(t) = \langle J, \dot{\gamma} \rangle \dot{\gamma}(t) = [\langle J, \dot{\gamma} \rangle(0) + \langle J', \dot{\gamma} \rangle(0) \cdot t] \cdot \dot{\gamma}(t).$$

•  $J^\perp$  is orthogonal to  $\dot{\gamma}$  pointwisely along  $\gamma$ .

• Let  $\mathcal{T} = \mathcal{T}_\gamma := \{ \text{Jacobi fields } J \text{ along } \gamma \}$ .

$$J^\perp := \{ J \in \mathcal{T} : J \perp \dot{\gamma} \}.$$

$$\mathcal{T}_0 := \{ J \in \mathcal{T} : J(0) = 0 \}$$

$$\mathcal{T}_0^\perp := \mathcal{T}^\perp \cap \mathcal{T}_0.$$

$$\cdot \quad \mathcal{T} = \mathcal{T}^\perp \oplus \left\{ (at + b) \cdot \dot{\gamma}(t) : a, b \in \mathbb{R} \right\}$$

$$\mathcal{T}_0 = \mathcal{T}_0^\perp \oplus \left\{ a \cdot t \cdot \dot{\gamma}(t) : a \in \mathbb{R} \right\}$$

$$\dim_{\mathbb{R}} \mathcal{T} = n^2, \quad \dim_{\mathbb{R}} \mathcal{T}_0 = n, \quad \dim_{\mathbb{R}} \mathcal{T}_0^\perp = n-1.$$

• Def. 6 (Conjugate point). • Let  $\gamma: [0, l] \rightarrow M$  be a unit speed geodesic.

• Let  $p = \gamma(0)$ . A point  $q = \gamma(t_0)$ ,  $t_0 \neq 0$ , is called a conjugate point of  $p$  along  $\gamma$ , if  $\exists$  non-trivial ( $\neq 0$ ) Jacobi field  $J$  along  $\gamma$ , s.t.

$$J(0) = J(t_0) = 0. \quad \#$$

•  $q$  conjugate to  $p$  along  $\gamma \Leftrightarrow p$  conjugate to  $q$  along  $\gamma^{-1}$ .

• Let  $q = \exp_p(t_0 \cdot v)$ ,  $v \in T_p M$ ,  $\gamma = \gamma_v(t) = \exp_p(t \cdot v)$ .

• Let  $w = J'(0) = \nabla_{\dot{\gamma}(0)} J(0) \neq 0$ , then:

$$\gamma(t, u) := \exp_p(t \cdot (v + u \cdot w)), \quad J(t) = \frac{\partial}{\partial u} \Big|_{u=0} \gamma(t, u).$$

• Hence from  $J(t_0) = 0$ , we have:

$$0 = J(t_0) = \frac{\partial}{\partial u} \Big|_{u=0} \gamma(t_0, u) = \frac{\partial}{\partial u} \Big|_{u=0} \exp_p(t_0 \cdot (v + u \cdot w))$$

$$= d(\exp_p)_{t_0 \cdot v}(t_0 \cdot w) = t_0 \cdot d(\exp_p)_{t_0 \cdot v}(w).$$

hence  $\exp_p$  degenerate at  $t_0 \cdot v$ .

- Suppose  $p$  has no conjugate point on time interval  $(0, l]$ .

Since  $\dim_{\mathbb{R}} \mathcal{T}_0^\perp = n-1$ , let  $J_1, \dots, J_{n-1} \in \mathcal{T}_0^\perp$  be a basis.

Then for each  $t \in (0, l]$ ,  $\{J_i(t)\}_{i=1}^{n-1}$  is a basis of  $\dot{\gamma}(t)^\perp$ .

- If for some  $t_0 \in (0, l]$ ,  $a_1, \dots, a_{n-1} \in \mathbb{R}$ , s.t.  $\sum_{i=1}^{n-1} a_i \cdot J_i(t_0) = 0$ .

Then  $\tilde{J} := \sum_{i=1}^{n-1} a_i J_i$  is Jacobi field along  $\gamma$  with  $\tilde{J}(0) = 0 = \tilde{J}'(t_0)$ .

Hence  $\tilde{J} \equiv 0$ , hence  $a_1 = \dots = a_{n-1} = 0$ .

### • §4.3. Space forms.

- Hyperbolic space  $\mathbb{H}^n$ , Poincaré model.

- $B_1 \subseteq \mathbb{R}^n$ , unit ball,  $B_1 := \{x = (x_1, \dots, x_n) : x_1^2 + \dots + x_n^2 < 1\}$ .

$$g_{\mathbb{H}^n} := \frac{4(dx_1^2 + \dots + dx_n^2)}{(1 - |x|^2)}, \quad \mathbb{H}^n := (B_1, g_{\mathbb{H}^n}).$$

- Upper half space model.

$$\mathbb{R}_n^+ := \{x = (x_1, \dots, x_n) = x_n > 0\},$$

$$g_{\mathbb{H}^n} = \frac{dx_1^2 + \dots + dx_n^2}{x_n^2}$$

- $g_{\mathbb{H}^n}$  is of constant sectional curvature  $-1$ .

## Theorem 7. (Uniformization).

- If  $(M^n, g)$  is a complete, simply connected Riem. mfd of constant sectional curvature  $\lambda$ , then:

- If  $\lambda = 0$ , then  $(M, g) \cong (\mathbb{R}^n, g_{\text{Euc}})$ , is the flat  $n$ -dim. Euclidean space.
- If  $\lambda > 0$ , there is a diffeomorphism  $\phi: M \rightarrow S^n$  such that  $\lambda^{-1} \cdot \phi^*(g_{S^n})$ , where  $g_{S^n}$  is the usual metric on the unit sphere  $S^n$  in  $\mathbb{R}^{n+1}$ :  $g_{S^n} = g_{\text{Euc}}|_{S^n}$ .
- If  $\lambda < 0$ , there is a diffeomorphism  $\phi: M \rightarrow H^n$  such that  $g = |\lambda|^{-1} \cdot \phi^*(g_{H^n})$ .

## Jacobi field on space form.

- Suppose  $(M^n, g)$  has constant sectional curvature  $K_0 \in \mathbb{R}$ . Then:

$$Rm(X, Y, Z, W) = K_0 \left( \langle X, Z \rangle \langle Y, W \rangle - \langle X, W \rangle \langle Y, Z \rangle \right)$$

$$R(X, Y)Z = K_0 \left( \langle Y, Z \rangle X - \langle X, Z \rangle Y \right).$$

- Jacobi eqn becomes:

$$\nabla_{\dot{\gamma}} \nabla_{\dot{\gamma}} J - K_0 \left( \langle J, \dot{\gamma} \rangle \dot{\gamma} - J \right) = 0.$$

- If  $\vec{J} \in T_{\gamma}(T_{\gamma})^{\perp}$ , then  $\vec{J}'' + K_0 \cdot \vec{J} = 0$ , then:

$$\vec{J}(t) = \begin{cases} a \cdot \frac{\sin(\sqrt{K_0} \cdot t)}{\sqrt{K_0}} \cdot e(t), & a \in \mathbb{R}, \text{ if } K_0 > 0. \\ a \cdot t \cdot e, & a \in \mathbb{R}, \text{ if } K_0 = 0 \\ a \cdot \frac{\sinh(\sqrt{-K_0} \cdot t)}{\sqrt{-K_0}} \cdot e(t), & \text{if } K_0 < 0. \end{cases}$$

for some unit parallel vector field  $e(t)$  along  $\gamma$  with  $e(0) \parallel \vec{J}'(0) \perp \vec{\gamma}'(0)$ ,

with initial value  $\vec{J}'(0) = a \cdot e(0)$ .

- Recall:  $\sinh x = \frac{e^x - e^{-x}}{2}$ ,  $\cosh x = \frac{e^x + e^{-x}}{2}$ .

