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## §2. Riemannian metric, Levi-Civita connection, Riem. curvature.

### §2.1. Riem. metric.

•  $M^n$ :  $n$ -dim diff. mfd.

•  $C^\infty(M) := \{ f: M \rightarrow \mathbb{R}, \text{ smooth function} \}$   $C^k(M)$ :  $k$ -diff

• Def 1. (Riem. metric). A Riem metric  $g$  on  $M$ , is given by an inner product

$\langle \cdot, \cdot \rangle_p$  (or  $g_p(\cdot, \cdot)$ ) on each  $T_p M$ , which varies smoothly in  $p \in M$ . That is,

$$\langle X, Y \rangle \in C^\infty(M), \quad \forall X, Y \in \Gamma(TM).$$

↑  
Smooth sections of  $\pi: TM \rightarrow M$ .

#.

• The Riem metric determines a positive, symmetric  $(2, 0)$ -tensor

$$g \in \Gamma(T^*M \otimes T^*M), \quad g(u, v) = \langle u, v \rangle_p, \quad \forall u, v \in T_p M.$$

$g$  is called Riem. metric.

• In local coord.  $\varphi: U \xrightarrow{\in \mathbb{R}^n} M$ ,  $x = (x^1, \dots, x^n)$ , put:

$$g_{ij} = g\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) = \left\langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right\rangle = g_{ij}.$$

Then  $(g_{ij})_{n \times n}$  is positive, symmetric matrix, varies smoothly on  $M$ , and

$$\forall X = X^i \frac{\partial}{\partial x^i}, \quad Y = Y^j \frac{\partial}{\partial x^j} \in \Gamma(TM),$$

$$g(X, Y) = g_{ij} X^i Y^j$$

$$g\left(X^i \frac{\partial}{\partial x^i}, Y^j \frac{\partial}{\partial x^j}\right) \\ = X^i Y^j g\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right).$$

• Locally,  $g = g_{ij} dx^i \otimes dx^j$ .

• Exp 2: Euclidean space  $\mathbb{R}^n$ ,  $g_{ij} = \delta_{ij}$ ,  $(x^1, \dots, x^n)$

$$g = \delta_{ij} \cdot dx^i \otimes dx^j = \sum_{i=1}^n dx^i \otimes dx^i. \quad \#$$

• Lemma 3 (Existence). Any diff. mfd  $M$  admits a Riem. metric.

• Proof: Take a countable, locally finite coord. covering  $\{(U_\alpha, \varphi_\alpha)\}$ ,  $U_\alpha \subseteq \mathbb{R}^n$

• Let  $\{f_\alpha\}$  be a partition of unity subordinated to  $\{(U_\alpha, \varphi_\alpha)\}$ .  
 $\sum_\alpha f_\alpha = 1$

• On each  $U_\alpha$ , let  $g_\alpha$  be the Euclidean metric on  $U_\alpha$ . Then put:

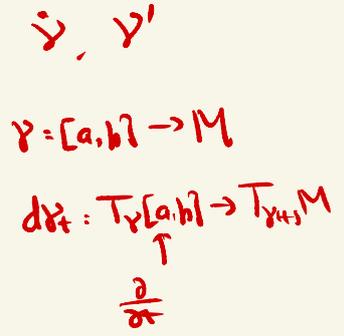
$$g = \sum_\alpha f_\alpha \cdot g_\alpha.$$



• Norm:  $|v|_g := \sqrt{\langle v, v \rangle} = \sqrt{g(v, v)}$ ,  $\forall v \in T_p M$ .

• Let  $\gamma: [a, b] \rightarrow M$  be a  $C^\infty$ -curve, define its length by:

$$L(\gamma) = \int_a^b |\dot{\gamma}(t)| dt, \quad \dot{\gamma}(t) := d\gamma_t \left( \frac{\partial}{\partial t} \right).$$



• §2.2. Levi-Civita connection.

• Prop. 4 (Def. of Levi-Civita connection).

• On any Riem. mfd  $(M, g)$ ,  $\exists!$  map:

gradient  $\nabla: \Gamma(TM) \times \Gamma(TM) \rightarrow \Gamma(TM), (X, Y) \mapsto \nabla_X Y$

satisfying:  $\forall X, Y, Z \in \Gamma(TM), f \in C^\infty(M)$ ,

(i).  $\nabla_X (Y+Z) = \nabla_X Y + \nabla_X Z$ .

(ii).  $\nabla_{fX+hY} Z = f \cdot \nabla_X Z + h \cdot \nabla_Y Z$ .

} linearity.

③.  $\nabla_X(fY) = f \cdot \nabla_X Y + X(f) \cdot Y$ . chain rule.

(ii).  $X\langle Y, Z \rangle = \langle \nabla_X Y, Z \rangle + \langle Y, \nabla_X Z \rangle$  compatible with metric.

(iii).  $\nabla_X Y - \nabla_Y X = [X, Y]$ . torsion free.

The map  $\nabla$  is called Levi-Civita connection.

Proof: We define  $\nabla$  by:  $\forall X, Y, Z \in \Gamma(TM)$ ,

(1).  $2\langle \nabla_X Y, Z \rangle := X\langle Y, Z \rangle + Y\langle Z, X \rangle - Z\langle X, Y \rangle - \langle X, [Y, Z] \rangle + \langle Y, [Z, X] \rangle + \langle Z, [X, Y] \rangle$

How to see (1): If we apply (ii) <sup>(iii)</sup>, then:  $X \leftarrow Y, Y \leftarrow Z, Z \leftarrow X$ .

(i).  $X\langle Y, Z \rangle = \langle \nabla_X Y, Z \rangle + \langle Y, \nabla_X Z \rangle$ .

(3).  $Y\langle Z, X \rangle = \langle \nabla_Y Z, X \rangle + \langle Z, \nabla_Y X \rangle$ .

(4).  $Z\langle X, Y \rangle = \langle \nabla_Z X, Y \rangle + \langle X, \nabla_Z Y \rangle$ .

apply (iii), (2) + (3) - (4) gives (1).

We check (i) ③ for example:

Recall:  $[fX, hY] = f h \cdot [X, Y] + f \cdot X(h) \cdot Y - h \cdot Y(f) \cdot X$ .

then we can compute:  $X\langle fY, Z \rangle$

$2\langle \nabla_X(fY), Z \rangle \stackrel{(1)}{=} X\langle fY, Z \rangle + fY\langle Z, X \rangle - Z\langle X, fY \rangle$

$- \langle X, [fY, Z] \rangle + \langle fY, [Z, X] \rangle + \langle Z, [X, fY] \rangle$

$= \{ \underbrace{X(f) \langle Y, Z \rangle + f X \langle Y, Z \rangle}_{\text{wavy}} \} + f \cdot \underbrace{Y \langle Z, X \rangle}_{\text{wavy}} - \{ \underbrace{Z(f) \langle X, Y \rangle + f \cdot Z \langle X, Y \rangle}_{\text{wavy}} \}$

$- \langle X, \underbrace{f \cdot [Y, Z] - Z(f) \cdot Y}_{\text{wavy}} \rangle + f \cdot \langle Y, \underbrace{[Z, X]}_{\text{wavy}} \rangle + \langle Z, \underbrace{f \cdot [X, Y] + X(f) \cdot Y}_{\text{wavy}} \rangle$

$= \underbrace{2f \cdot \langle \nabla_X Y, Z \rangle}_{\text{wavy}} + 2 X(f) \cdot \langle Y, Z \rangle$

$$= \langle 2f \cdot \nabla_X \gamma + 2X(f) \cdot \gamma, Z \rangle.$$

$$\Rightarrow \nabla_X (f\gamma) = f \cdot \nabla_X \gamma + X(f) \cdot \gamma.$$



• Calculate in local coord.:  $\varphi: U \xrightarrow{\cong \mathbb{R}^n} M$ ,  $x = (x^1, \dots, x^n)$ .

• Christoffel Symbols:  $\nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} = \Gamma_{ij}^k \frac{\partial}{\partial x^k}$ .

• For  $X = X^i \frac{\partial}{\partial x^i}$ ,  $\gamma = \gamma^j \frac{\partial}{\partial x^j}$ .

$$\nabla_X \gamma = \nabla_{X^i \frac{\partial}{\partial x^i}} \left( \gamma^j \frac{\partial}{\partial x^j} \right) = X^i \cdot \nabla_{\frac{\partial}{\partial x^i}} \left( \gamma^j \frac{\partial}{\partial x^j} \right).$$

$$= X^i \cdot \left( \frac{\partial \gamma^j}{\partial x^i} \frac{\partial}{\partial x^j} + \gamma^j \cdot \Gamma_{ij}^k \frac{\partial}{\partial x^k} \right)$$

$$= X^i \cdot \left( \frac{\partial \gamma^k}{\partial x^i} + \gamma^j \cdot \Gamma_{ij}^k \right) \cdot \frac{\partial}{\partial x^k}.$$

• Def. 5 (Covariant derivative). •  $X \in \Gamma(TM)$ ,  $v \in T_p M$ ,

define  $\nabla_v X$  as follows:

• Extend  $v$  to a vector field  $V \in \Gamma(TM)$ , then put:

$$\nabla_v(X) := \nabla_V X(p) \in T_p M.$$

#.

• Let  $\gamma: I \rightarrow M$  be a diff. curve.  $X \in \Gamma(TM)$ .

Then  $\nabla_{\dot{\gamma}} X$  depend only on values of  $X$  along  $\gamma$ , since:

$$\langle \nabla_{\dot{\gamma}} X, \gamma \rangle = \dot{\gamma} \langle X, \gamma \rangle - \langle X, \nabla_{\dot{\gamma}} \gamma \rangle$$

$$= \frac{d}{dt} \langle X, \gamma \rangle (\gamma(t)) - \langle X, \nabla_{\dot{\gamma}} \gamma \rangle.$$

• Lemma 6. • In local coord.  $\varphi: U \xrightarrow{\cong \mathbb{R}^n} M$ ,  $x = (x^1, \dots, x^n)$ .



$$\begin{cases} \Gamma_{ij}^k = \frac{1}{2} g^{kl} (\partial_i g_{jl} + \partial_j g_{il} - \partial_l g_{ij}) \\ \partial_k g_{ij} = g_{il} \Gamma_{jk}^l + g_{jl} \Gamma_{ik}^l \end{cases}$$

where  $(g^{ij})_{n \times n} = (g_{ij})_{n \times n}^{-1}$  denotes the inverse matrix.

• Proof:  $\cdot \left[ \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = \frac{\partial^2}{\partial x^i \partial x^j} - \frac{\partial^2}{\partial x^j \partial x^i} = 0.$

• Then, from Egn. (1).

$$\left\langle \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^l} \right\rangle = \frac{1}{2} \cdot \left\{ \frac{\partial}{\partial x^i} \left\langle \frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^l} \right\rangle + \frac{\partial}{\partial x^j} \left\langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^l} \right\rangle - \frac{\partial}{\partial x^l} \left\langle \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right\rangle \right\}$$

$$\parallel \left\langle \Gamma_{ij}^k \frac{\partial}{\partial x^k}, \frac{\partial}{\partial x^l} \right\rangle$$

$$\parallel g_{kl} \Gamma_{ij}^k = \frac{1}{2} \cdot \left\{ \partial_i g_{jl} + \partial_j g_{il} - \partial_l g_{ij} \right\} \Rightarrow \text{1st identity.}$$

$$\left. \begin{aligned} 2 g_{kl} \Gamma_{ij}^k &= \partial_i g_{jl} + \partial_j g_{il} - \partial_l g_{ij} \\ 2 g_{kj} \Gamma_{il}^k &= \partial_i g_{jl} + \partial_l g_{ij} - \partial_j g_{il} \end{aligned} \right\} \Rightarrow \text{2nd identity.}$$



## § 2.3. Riem. curvature.

• Def 7: (Riem. curvature). Define:

$$\mathcal{R}: \Gamma(TM) \times \Gamma(TM) \times \Gamma(TM) \rightarrow \Gamma(TM),$$

$$(X, Y, Z) \mapsto \mathcal{R}(X, Y)Z := \nabla_X(\nabla_Y Z) - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z.$$

• Or:

$$R_m: \Gamma(TM) \times \Gamma(TM) \times \Gamma(TM) \times \Gamma(TM) \rightarrow C^\infty(M),$$

$$(X, Y, Z, W) \mapsto R_m(X, Y, Z, W) := \langle \mathcal{R}(X, Y)W, Z \rangle$$

• Prop 8. (i).  $R$  and  $R_m$  is  $C^\infty$ -linear in each variable.

(ii).  $R_m(X, Y, Z, W) = -R_m(Y, X, Z, W)$

$= -R_m(X, Y, W, Z) = R_m(Z, W, X, Y).$

(iii). (1st Bianchi identity).

$X \mapsto Y, Y \mapsto Z, Z \mapsto W.$

•  $R(X, Y)Z + R(Y, Z)X + R(Z, X)Y = 0.$

•  $R_m(X, Y, Z, W) + R_m(Y, Z, X, W) + R_m(Z, X, Y, W) = 0.$

• Proof:

(i).  $f \in C^\infty(M)$ , then:

$R(fX, Y)Z = \nabla_{fX} \nabla_Y Z - \nabla_Y \nabla_{fX} Z - \nabla_{[fX, Y]} Z$

$= f \cdot \nabla_X \nabla_Y Z - \nabla_Y (f \cdot \nabla_X Z) - \nabla_{f[X, Y] - Y(f)X} Z$

$= f \cdot \nabla_X \nabla_Y Z - (f \cdot \nabla_Y \nabla_X Z + Y(f) \cdot \nabla_X Z) - (f \cdot \nabla_{[X, Y]} Z - Y(f) \cdot \nabla_X Z)$

$= f \cdot R(X, Y)Z.$

(ii). We can compute:

$R_m(X, Y, Z, W) + R_m(X, Y, W, Z)$   $\langle \nabla_X \nabla_Y W, Z \rangle = X \langle \nabla_Y W, Z \rangle - \langle \nabla_Y W, \nabla_X Z \rangle$

$= \langle \nabla_X \nabla_Y W - \nabla_Y \nabla_X W - \nabla_{[X, Y]} W, Z \rangle + \langle \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z, W \rangle$

$= \left\{ X \langle \nabla_Y W, Z \rangle - \langle \nabla_Y W, \nabla_X Z \rangle \right\} - \left\{ Y \langle \nabla_X W, Z \rangle - \langle \nabla_X W, \nabla_Y Z \rangle \right\} - \langle \nabla_{[X, Y]} W, Z \rangle$

$+ \left\{ X \langle \nabla_Y Z, W \rangle - \langle \nabla_Y Z, \nabla_X W \rangle \right\} - \left\{ Y \langle \nabla_X Z, W \rangle - \langle \nabla_X Z, \nabla_Y W \rangle \right\} - \langle \nabla_{[X, Y]} Z, W \rangle$

$= X Y \langle Z, W \rangle - Y X \langle Z, W \rangle - [X, Y] \langle Z, W \rangle = 0.$

• torsion free:

$$\nabla_X Y - \nabla_Y X = [X, Y]$$

(iii)  $R(X, Y)Z + R(Y, Z)X + R(Z, X)Y$

$$= \left( \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z \right) + \left( \nabla_Y \nabla_Z X - \nabla_Z \nabla_Y X - \nabla_{[Y, Z]} X \right)$$

$$+ \left( \nabla_Z \nabla_X Y - \nabla_X \nabla_Z Y - \nabla_{[Z, X]} Y \right)$$

$$= \nabla_X [Y, Z] + \nabla_Y [Z, X] + \nabla_Z [X, Y] - \nabla_{[X, Y]} Z - \nabla_{[Y, Z]} X - \nabla_{[Z, X]} Y$$

$$= [X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]]$$

$$= 0 \quad \leftarrow \text{Jacobi identity.}$$



• In local coord., denote:

$$R\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) \frac{\partial}{\partial x^l} = R_{ij}{}^k{}_l \cdot \frac{\partial}{\partial x^k}$$

then:

$$R_{ijkl} = R_m\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^k}, \frac{\partial}{\partial x^l}\right) = \int_{ks} R_{ij}{}^s{}_l$$

From Prop. 8, we have:

$$i < j, j < l, l < i$$

$$i < j, j < k, k < i$$

$$\cdot R_{ijke} + R_{jkil} + R_{kijl} = 0$$

$$\cdot R_{ijke} = -R_{jike} = -R_{ijlk} = R_{klij}$$

• For vector fields,  $R_m(X, Y, Z, W) = R_{ijke} X^i Y^j Z^k W^l$

•  $C^\infty(M)$ -linearity implies that  $R$  defines a  $(3, 1)$ -tensor ( $R_m$  a  $(4, 0)$ -tensor)

Def 9. (Sectional curvature).

• Let  $p \in M$ ,  $\bar{P} \subset T_p M$  be a plane,  $u, v \in \bar{P}$  linear indep. vectors.

• Define the sectional curvature of  $\bar{P}$ :

$$K(\bar{P}) := \frac{R_m(u, v, u, v)}{|u \wedge v|^2}$$

here:

$$|u \wedge v|^2 = |u|^2 \cdot |v|^2 - \langle u, v \rangle^2 = \det \begin{pmatrix} \langle u, u \rangle & \langle u, v \rangle \\ \langle u, v \rangle & \langle v, v \rangle \end{pmatrix}.$$

•  $K(\bar{P})$  does not depend on the choice of  $u$  and  $v$ .

Proof: • Choose orthonormal basis  $e_1, e_2 \in \bar{P}$ , then write: g<sub>p</sub> inner product in T<sub>p</sub>M

$$u = u_1 e_1 + u_2 e_2, \quad v = v_1 e_1 + v_2 e_2.$$

• Then we can compute:

$$R_m(u, v, u, v) = R_m(u_1 e_1 + u_2 e_2, v_1 e_1 + v_2 e_2, u_1 e_1 + u_2 e_2, v_1 e_1 + v_2 e_2)$$

$$= R_{1212} u_1^2 v_2^2 + R_{1221} u_1 u_2 v_1 v_2 + R_{2112} u_1 u_2 v_1 v_2 + R_{2121} u_2^2 v_1^2$$

$$= R_{1212} \cdot \left\{ \begin{array}{l} -R_{1212} \\ -R_{1112} \\ R_{1212} \end{array} \right\} \left\{ u_1^2 v_2^2 + u_2^2 v_1^2 - 2u_1 u_2 v_1 v_2 \right\}$$

$$= R_{1212} \cdot \left\{ (u_1^2 + u_2^2) \cdot (v_1^2 + v_2^2) - (u_1 v_1 + u_2 v_2)^2 \right\}$$

$$= R_{1212} \cdot |u \wedge v|^2.$$

Hence  $K(\bar{P})$  does not depend on the choice of  $u$  and  $v$ . □

Lemma 10. We have:

$s, t$

$$\frac{\partial^2}{\partial s \partial t} (s) = 0.$$

$$\frac{\partial^2}{\partial s \partial t} (s^2 + t) \Big|_{s=0, t=0} = 0.$$

$$6 R_m(X, Y, Z, W) = \frac{\partial^2}{\partial s \partial t} \Big|_{s=t=0} \left( R_m(X+sZ, Y+tW, X+sZ, Y+tW) - R_m(X+sW, Y+tZ, X+sW, Y+tZ) \right) \quad \begin{array}{l} \swarrow \\ Z \leftrightarrow W \end{array}$$

Proof: • By linearity, coefficient of  $s \cdot t$  on the RHS is:

$$\begin{aligned}
& R_m(\underline{Z, W, X, Y}) + R_m(\underline{Z, Y, X, W}) + R_m(\underline{X, W, Z, Y}) + R_m(\underline{X, Y, Z, W}) \quad \downarrow Z \leftrightarrow W \\
& - R_m(\underline{W, Z, X, Y}) - R_m(\underline{W, Y, X, Z}) - R_m(\underline{X, Z, W, Y}) - R_m(\underline{X, Y, W, Z}) \\
& = 4 R_m(\underline{X, Y, Z, W}) - (R_m(\underline{Y, Z, X, W}) + R_m(\underline{W, Y, X, Z})) \\
& \quad - (R_m(\underline{W, X, Z, Y}) + R_m(\underline{W, Y, X, Z})) \quad \begin{array}{l} \xrightarrow{=} -R_m(\underline{Z, W, X, Y}) \\ \xrightarrow{=} -R_m(\underline{W, Z, Y, X}) \end{array} \\
& \quad \quad \quad \text{1st Bianchi identity} \\
& = 6 R_m(X, Y, Z, W).
\end{aligned}$$

• All other terms are zero under  $\frac{\partial^2}{\partial s \partial t} \Big|_{s=t=0}$ . □

• Corollary 11. If for some  $K_0 \in \mathbb{R}$ ,  $K \equiv K_0$  at  $p \in M$ , then:

$$R_m(X, Y, Z, W) = K_0 \cdot \left\{ \langle X, Z \rangle \cdot \langle Y, W \rangle - \langle X, W \rangle \cdot \langle Y, Z \rangle \right\}$$

Proof: • From the def. of sectional curvature  $K$ , we have:

$$R_m(X, Y, X, Y) = K_0 \cdot |X \wedge Y|^2 = K_0 \cdot (|X|^2 \cdot |Y|^2 - \langle X, Y \rangle^2)$$

• Hence, the RHS of Lemma 10 is:

$$\begin{aligned}
& R_m(X+sZ, Y+tW, X+sZ, Y+tW) - R_m(X+sW, Y+tZ, X+sW, Y+tZ) \\
& = K_0 \cdot \left\{ |X+sZ|^2 \cdot |Y+tW|^2 - \langle X+sZ, Y+tW \rangle^2 \right\} \\
& \quad - K_0 \cdot \left\{ |X+sW|^2 \cdot |Y+tZ|^2 - \langle X+sW, Y+tZ \rangle^2 \right\} \quad \downarrow Z \leftrightarrow W
\end{aligned}$$

$$\cdot |X+sZ|^2 \cdot |Y+tW|^2 = (|X|^2 + 2s \langle X, Z \rangle + s^2 |Z|^2) \cdot (|Y|^2 + 2t \langle Y, W \rangle + t^2 |W|^2)$$

$$\cdot \langle X+sZ, Y+tW \rangle^2 = (\langle X, Y \rangle + t \langle X, W \rangle + s \langle Z, Y \rangle + st \langle W, Z \rangle)^2$$

$$= s.t. \left[ 4 \langle X, Z \rangle \cdot \langle Y, W \rangle - 2 \langle X, W \rangle \cdot \langle Y, Z \rangle - 2 \langle X, Y \rangle \cdot \langle W, Z \rangle \right. \\ \left. - 4 \langle X, W \rangle \cdot \langle Y, Z \rangle + 2 \langle X, Z \rangle \cdot \langle Y, W \rangle + 2 \langle X, Y \rangle \cdot \langle W, Z \rangle \right]$$

↕  $Z \leftrightarrow W$ .

+ other order terms

$$= s.t. \left[ 6 \langle X, Z \rangle \cdot \langle Y, W \rangle - 6 \langle X, W \rangle \cdot \langle Y, Z \rangle \right] + \text{other order terms.}$$

$$=: f(s, t).$$

• Hence from Lemma 10,

$$6 \text{Rm}(X, Y, Z, W) = \frac{\partial^2}{\partial s \partial t} \Big|_{s=t=0} f(s, t)$$

$$= 6 \cdot \left( \langle X, Z \rangle \cdot \langle Y, W \rangle - \langle X, W \rangle \cdot \langle Y, Z \rangle \right).$$

□

• Prop. 12. In local coord.  $x = (x^1, \dots, x^n)$ , we have:

$$\cdot R_{ij}^k{}_l = \frac{\partial \Gamma_{jl}^k}{\partial x^i} - \frac{\partial \Gamma_{il}^k}{\partial x^j} + \Gamma_{jl}^r \Gamma_{ir}^k - \Gamma_{il}^r \Gamma_{jr}^k$$

$$R_{ijkl} = \nabla_{ks} R_{ij}^s{}_l$$

$$\cancel{R_{ijkl} = \nabla_{ks}}$$

$$\cdot R_{ijkl} = -\frac{1}{2} \left( \frac{\partial^2 g_{ik}}{\partial x^j \partial x^l} + \frac{\partial^2 g_{jl}}{\partial x^i \partial x^k} - \frac{\partial^2 g_{il}}{\partial x^j \partial x^k} - \frac{\partial^2 g_{jk}}{\partial x^i \partial x^l} \right)$$

$$- g_{rs} \left( \Gamma_{ik}^r \Gamma_{jl}^s - \Gamma_{il}^r \Gamma_{jk}^s \right).$$

• Proof: • From  $\left[ \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = 0$ , we have:

$$R_{ij}^k{}_l \cdot \frac{\partial}{\partial x^k} = R \left( \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right) \frac{\partial}{\partial x^l}$$

$$= \nabla_{\frac{\partial}{\partial x^i}} \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^l} - \nabla_{\frac{\partial}{\partial x^j}} \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^l}$$

$$= \nabla_{\frac{\partial}{\partial x^i}} \left( \Gamma_{jl}^k \cdot \frac{\partial}{\partial x^k} \right) - \nabla_{\frac{\partial}{\partial x^j}} \left( \Gamma_{il}^k \cdot \frac{\partial}{\partial x^k} \right)$$

$$\begin{aligned}
&= \frac{\partial \Gamma_{jl}^k}{\partial x^i} \cdot \frac{\partial}{\partial x^k} + \Gamma_{jl}^k \cdot \Gamma_{ik}^r \cdot \frac{\partial}{\partial x^r} - \frac{\partial \Gamma_{il}^k}{\partial x^j} \cdot \frac{\partial}{\partial x^k} - \Gamma_{il}^k \cdot \Gamma_{jk}^r \cdot \frac{\partial}{\partial x^r} \\
&\quad \begin{array}{c} \uparrow \\ k \leftrightarrow r \end{array} \qquad \begin{array}{c} \uparrow \\ k \leftrightarrow r \end{array} \\
&= \left( \frac{\partial \Gamma_{jl}^k}{\partial x^i} - \frac{\partial \Gamma_{il}^k}{\partial x^j} + \Gamma_{jl}^r \cdot \Gamma_{ir}^k - \Gamma_{il}^r \cdot \Gamma_{jr}^k \right) \cdot \frac{\partial}{\partial x^k}.
\end{aligned}$$

• Next.

$$R_{ijkl} = R_m \left( \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}, \frac{\partial}{\partial x^k}, \frac{\partial}{\partial x^l} \right)$$

$$= \left\langle R \left( \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right) \frac{\partial}{\partial x^l}, \frac{\partial}{\partial x^k} \right\rangle$$

$$= \left\langle \nabla_{\frac{\partial}{\partial x^i}} \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^l} - \nabla_{\frac{\partial}{\partial x^j}} \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^l}, \frac{\partial}{\partial x^k} \right\rangle$$

$$= \frac{\partial}{\partial x^i} \left\langle \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^l}, \frac{\partial}{\partial x^k} \right\rangle - \frac{\partial}{\partial x^j} \left\langle \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^l}, \frac{\partial}{\partial x^k} \right\rangle \quad \text{--- ①}$$

$$- \left\langle \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^l}, \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^k} \right\rangle + \left\langle \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^l}, \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^k} \right\rangle \quad \text{--- ②}$$

• ② is  $\Gamma$ -terms.

$$\textcircled{2} = - \Gamma_{jl}^r \cdot \Gamma_{ik}^s \cdot g_{rs} + \Gamma_{il}^r \cdot \Gamma_{jk}^s \cdot g_{rs}.$$

$$\textcircled{1} = \frac{\partial}{\partial x^i} \left\langle \Gamma_{jl}^r \cdot \frac{\partial}{\partial x^r}, \frac{\partial}{\partial x^k} \right\rangle - \frac{\partial}{\partial x^j} \left\langle \Gamma_{il}^r \cdot \frac{\partial}{\partial x^r}, \frac{\partial}{\partial x^k} \right\rangle$$

$$= \frac{\partial}{\partial x^i} \left( g_{kr} \cdot \Gamma_{jl}^r \right) - \frac{\partial}{\partial x^j} \left( g_{kr} \cdot \Gamma_{il}^r \right)$$

$$= \frac{\partial}{\partial x^i} \frac{1}{2} \cdot \left( \partial_r g_{jk} + \partial_j g_{rk} - \partial_k g_{jr} \right) - \frac{\partial}{\partial x^j} \frac{1}{2} \cdot \left( \partial_l g_{ik} + \partial_i g_{lk} - \partial_k g_{il} \right).$$

$$= \frac{1}{2} \cdot \left( \frac{\partial^2 g_{jk}}{\partial x^i \partial x^l} - \frac{\partial^2 g_{jl}}{\partial x^i \partial x^k} - \frac{\partial^2 g_{ik}}{\partial x^j \partial x^l} + \frac{\partial^2 g_{il}}{\partial x^j \partial x^k} \right).$$



• Ricci curvature: Let  $\{e_i\}_{i=1}^n$  be an orthonormal basis. Define:

$$\text{Ric}(X, Y) := \sum_{i=1}^n R_m(X, e_i, Y, e_i)$$

• In local coord  $x = (x^1, \dots, x^n)$ ,

$$\text{Ric}(X, Y) = g^{ij} \cdot R_m(X, \frac{\partial}{\partial x^i}, Y, \frac{\partial}{\partial x^j}).$$

• Write:

$$R_{ij} = \text{Ric}\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) = g^{pp} \cdot R_{zppj} \quad \#$$

• A Riem. mfd  $(M, g)$  satisfying:

$$\text{Ric} \equiv \lambda \cdot g, \quad \lambda \in \mathbb{R}.$$

is called an Einstein mfd.

• Scalar curvature:  $S := g^{ij} \cdot R_{ij}$ .

• Exp 13: Euclidean space  $\mathbb{R}^n$ :

$$g_{ij} = \delta_{ij}, \quad \Gamma_{ij}^k = 0, \quad R_m \equiv 0. \quad \#$$

•  $f \in C^\infty(M)$ :

•  $\nabla f$ : gradient field of  $f$ , defined by:

$$\langle \nabla f, X \rangle = X(f), \quad \forall X \in \Gamma(TM)$$

Locally,  $\nabla f = g^{ij} \cdot \frac{\partial f}{\partial x^i} \cdot \frac{\partial}{\partial x^j}$ .

$$df = \frac{\partial f}{\partial x^i} dx^i, \quad |\nabla f|^2 = |df|^2$$

- Hess(f): Hessian tensor, defined by:

$$\text{Hess}(f)(X, Y) = X(Yf) - (\nabla_X Y)f, \quad \forall X, Y \in \Gamma(TM).$$

• Hess(f) is  $C^\infty$ -linear in X, Y.

• Hess(f) is symmetric in X, Y:  $\text{Hess}(f)(X, Y) = \text{Hess}(f)(Y, X)$ .

$$\begin{aligned} & \text{Hess}(f)(X, Y) - \text{Hess}(f)(Y, X) \\ &= X(Yf) - Y(Xf) - (\nabla_X Y - \nabla_Y X)f \stackrel{\text{torsion free}}{=} 0. \end{aligned}$$

• Locally, we write:

$$\nabla_i := \frac{\partial}{\partial x^i}$$

$$\text{Hess}(f) = \nabla_i \nabla_j f \cdot dx^i \otimes dx^j,$$

$$\text{where: } \nabla_i \nabla_j f = \frac{\partial^2 f}{\partial x^i \partial x^j} - \Gamma_{ij}^k \cdot \frac{\partial f}{\partial x^k}.$$

$$\Delta f := \text{tr}_g \text{Hess}(f) = g^{ij} \cdot \nabla_i \nabla_j f.$$

### • Exp 14 (Conformal change).

•  $g$ : Riem. metric,  $f \in C^\infty(M)$ ,  $\tilde{g} := e^f \cdot g$  is also a Riem. metric.

• In local coord.  $x = (x^1, \dots, x^n)$ ,  $g_{ij}, \tilde{g}_{ij}, \Gamma_{ij}^k, \tilde{\Gamma}_{ij}^k, R_m, \tilde{R}_m, \dots$

$$\tilde{\Gamma}_{ij}^k = \Gamma_{ij}^k + \frac{1}{2} \cdot \left( f_i \cdot \delta_{jk} + f_j \cdot \delta_{ik} - f_k \cdot g^{kl} \cdot g_{ij} \right).$$

$$\tilde{R}_m = e^f \cdot \left[ R_m - \frac{1}{2} \cdot \left( \text{Hess}(f) - \frac{df \otimes df}{2} \right) \otimes g - \frac{|df|^2}{8} \cdot g \otimes g \right].$$

here,  $\otimes$  is the Kulkarni-Nomizu product:

for symmetric (2,0) tensors  $\alpha, \beta$ , define  $\alpha \otimes \beta$  to be the (4,0)-tensor:

$$\alpha \textcircled{\wedge} \beta (u, v, w, z) = \alpha(u, w) \cdot \beta(v, z) - \alpha(u, z) \cdot \beta(v, w) \\ + \alpha(v, z) \cdot \beta(u, w) - \alpha(v, w) \cdot \beta(u, z).$$

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